

Betweenness preserving permutations.

We let

ι

be the identity map of the set of points.

Definition. We say a permutation τ of the set of points is **betweenness preserving** if

$$\tau[\mathbf{s}(a, b)] = \mathbf{s}(\tau(a), \tau(b)) \text{ whenever } a \text{ and } b \text{ are distinct points.}$$

We let

\mathcal{B}

be the set of betweenness preserving permutations of the set of points.

Theorem. \mathcal{B} is a subgroup of the group of permutations of the set of points.

Proof. Exercise. \square

Remark. We will use repeatedly the fact that if $\tau \in \mathcal{B}$ and X is a set of points then

$$\tau^{-1}[\tau[X]] = (\tau^{-1} \circ \tau)[X] = \iota[X] = X.$$

Proposition. Suppose A is a set of points and $\tau \in \mathcal{B}$. Then

$$\tau[\mathbf{b}(A)] = \mathbf{b}(\tau[A]).$$

Proof. Suppose $y \in \tau[\mathbf{b}(A)]$. Then there is x in $\mathbf{b}(A)$ such that $y = \tau(x)$. Since $x \in \mathbf{b}(A)$ there is a in A such that $\mathbf{s}(a, x) \subset A$. Let $b = \tau(a)$ and note that $b \in \tau[A]$. Since $\tau \in \mathcal{B}$ we have $\tau[\mathbf{s}(a, x)] = \mathbf{s}(\tau(a), \tau(x)) = \mathbf{s}(b, y)$. Were it the case that $y \in \tau[A]$ we would have $x = \tau^{-1}(y) \in \tau^{-1}[\tau[A]] = A$ which is impossible since $x \in \mathbf{b}(A)$ implies $x \notin A$. Thus $y \in \mathbf{b}(\tau[A])$.

Suppose $y \in \mathbf{b}(\tau[A])$. Then $y \notin \tau[A]$ and there is b in $\tau[A]$ such that $\mathbf{s}(b, y) \subset \tau[A]$. Let $x = \tau^{-1}(y)$ and let $a = \tau^{-1}(b)$. Were it the case that $x \in A$ we would have $y = \tau(x) \in \tau[A]$ which is impossible. Moreover, $a = \tau^{-1}(b) \in \tau^{-1}[\tau[A]] = A$. Since $\tau^{-1} \in \mathcal{B}$ we have $\mathbf{s}(a, x) = \mathbf{s}(\tau^{-1}(b), \tau^{-1}(y)) = \tau^{-1}[\mathbf{s}(b, y)] \subset \tau^{-1}[\tau[A]] = A$. Thus $x \in \mathbf{b}(A)$ so $y = \tau(x) \in \tau[\mathbf{b}(A)]$. \square

Theorem. Suppose τ is a betweenness preserving permutation of the set of points. The following statements hold:

(i) If a and b are distinct points then $\tau[\mathbf{l}(a, b)] = \mathbf{l}(\tau(a), \tau(b))$; in particular, if L is a line then $\tau[L]$ is a line.

(ii) If o and a are distinct points then $\tau[\mathbf{r}(o, a)] = \mathbf{r}(\tau(o), \tau(a))$. In particular, if R is a ray then $\tau[R]$ is a ray and $\tau(\mathbf{o}(R)) = \mathbf{o}(\tau[R])$.

(iii) If L is a line and a is a point not on L . Then $\tau(a)$ is not on $\tau[L]$ and $\tau[\mathbf{h}(L, a)] = \mathbf{h}(\tau[L], \tau(a))$. In particular, if H is a half space then $\tau[H]$ is a half space and $\tau[\mathbf{b}(H)] = \mathbf{b}(\tau[H])$.

(iv) If $<$ is an geometric linear ordering of the line L then

$$\{(\tau(a), \tau(b)) : a, b \in L \text{ and } a < b\}$$

is a geometric ordering of the line $\tau[L]$.

(v) If F is an fundamental set then $\tau[F]$ is an fundamental set; if S is a side of F then $\tau[S]$ is a side of $\tau[F]$; if v is a vertex of F then $\tau(v)$ is a vertex of $\tau[F]$.

Proof. Exercise. \square

Definition. Suppose $\tau \in \mathcal{B}$, L is a line and $\tau[L] = L$. As a consequence of (iv) in the preceding Theorem we see that *either*

$$\tau(a) < \tau(b) \Leftrightarrow a < b$$

whenever $<$ is a geometric linear ordering of L and $a, b \in L$ in which case we say τ is **order preserving on L** or

$$\tau(b) < \tau(a) \Leftrightarrow a < b$$

whenever $<$ is a geometric linear ordering of L and $a, b \in L$ in which case we say τ is **order reversing on L** .

Here are three very important consequences of the Continuity Axiom.

Theorem. Suppose

- (i) $\tau \in \mathcal{B}$, L is a line, $\tau[L] = L$ and τ is order preserving on L ;
- (ii) $\tau(a) \neq a$ for each $a \in L$; and
- (iii) $o \in L$ and $<$ is the geometric linear ordering of L such that $o < \tau(o)$.

Then for each $a \in L$ there is a unique integer n such that

$$\tau^n(o) \leq a < \tau^{n+1}(o).$$

Moreover,

$$a < \tau(a) \quad \text{for } a \in L.$$

Proof. Let $R = \{x \in L : o < x\}$. Let $A = \{\tau^n(o) : n \in \mathbf{N}\}$. Since τ preserves $<$ we find that $A \subset R$.

Suppose $a \in R$. By an earlier Theorem, a is not an upper bound for A so there is a least nonnegative integer n such that $a < \tau^{n+1}(o)$. It follows that $\tau^n(o) \leq a$. Thus $\tau^n(o) \leq a < \tau^{n+1}(o)$. The uniqueness of n follows directly from the fact that τ preserved $<$ as does the fact that $\tau^{n+1}(o) \leq \tau(a)$ so $a < \tau(a)$.

In case $a = o$ the assertion to be proved is trivial.

In case $a \in R^o$ we apply the results of the first paragraph with τ replaced by τ^{-1} . \square

Theorem. Suppose $\tau \in \mathcal{B}$, L is a line, $\tau[L] = L$ and τ is order reversing on L .

Then there is a point o in L such that $\tau(o) = o$.

Proof. This follows directly from earlier theory. \square

Theorem. Suppose (H, R) is a flag, o is the origin of R , $\tau \in \mathcal{B}$, $\tau(o) = o$,

$$R \subset \tau[H] \quad \text{and} \quad \tau[R] \subset H.$$

Then there is S such that $S \in \mathbf{R}(o)$, $S \subset \mathbf{a}(R, \tau[R])$ and

$$\tau[S] = S.$$

Proof. Let \prec be the geometric linear ordering on $\mathbf{A}(H, R)$ and recall that, by a previous Theorem, \prec is complete. We have $\tau^2[R] \subset \tau[H]$ so $\tau^2[H] \in \mathbf{A}(H, R)$. Thus *either* $\tau^2[R] \subset \mathbf{a}(\tau[R], R)$ or $R \subset \mathbf{a}(\tau[R], \tau^2[R])$.

Suppose $(\tau^2[R] \subset \mathbf{a}(\tau[R], R))$ holds. Let $\mathcal{T} = \{S \in \mathbf{A}(H, R) : S \prec R\}$. We have

$$S \in \mathcal{T} \Rightarrow S \subset \mathbf{a}(\tau[R], R) \Rightarrow \tau[S] \in \mathbf{a}(\tau[R], \tau^2[R]) \Rightarrow \tau[S] \prec \tau^2[R] \Rightarrow \tau[S] \prec R \Rightarrow \tau[S] \in \mathcal{T}.$$

Moreover, by an earlier Theorem,

$$S, T \in \mathcal{T} \text{ and } S \prec T \Rightarrow S \subset \mathbf{a}(\tau[R], T) \Rightarrow T \in \mathbf{a}(R, S) \Rightarrow \tau[T] \subset \mathbf{a}(\tau[R], \tau[S]) \Rightarrow \tau[T] \prec \tau[S].$$

Thus

$$\{(S, \tau[S]) : S \in \mathcal{T}\}$$

is order reversing function from \mathcal{T} to itself. By earlier theory, there is a member S of \mathcal{T} such that $\tau[S] = S$.

Suppose $R \subset \mathbf{a}(\tau[R], \tau^2[R])$ holds. Let $U = \tau[R]$ and let $I = \tau[H]$ and let $\sigma = \tau^{-1}$. Then

$$U \subset \sigma[I], \quad \sigma[U] \subset I, \quad \sigma^2[U] \subset \mathbf{a}(\sigma[U], U)$$

so we may apply the result just obtained with τ, R, H replaced by σ, U, I to secure $S \in \mathbf{R}(o)$ such that $\sigma[S] = S$ and $S \subset \mathbf{a}(U, \sigma[U])$. It follows that $\tau[S] = S$ and $S \subset \mathbf{a}(R, \tau[R])$.

Orientation.

Let o be a point.

Definition. We let

$$\mathbf{F}(o) = \{(H, R) : (H, R) \text{ is a flag and } o = \mathbf{o}(R)\}.$$

Definition. Let

$$\mathbf{K} = \{(1, 1), (1, -1), (-1, 1), (-1, -1)\} \quad \text{and let} \quad \mathbf{K}^+ = \{(1, 1), (-1, -1)\}.$$

Note that

$$(ac, bd) \in \mathbf{K} \quad \text{whenever} \quad (a, b), (c, d) \in \mathbf{K}.$$

For each flag $F = (H, R)$ and each $(a, b) \in \mathbf{K}$ we let

$$F^{(a,b)} = \begin{cases} (H, R) & \text{if } (a, b) = (1, 1); \\ (H, R^\circ) & \text{if } (a, b) = (1, -1); \\ (H^\circ, R) & \text{if } (a, b) = (-1, 1); \\ (H^\circ, R^\circ) & \text{if } (a, b) = (-1, -1). \end{cases}$$

Note that

$$(1) \quad F^{(a,b)}{}^{(c,d)} = F^{(ac, bd)} \quad \text{whenever} \quad (a, b), (c, d) \in \mathbf{K}.$$

Definition. $G = (I, S) \in \mathbf{F}(o)$. We let

$$\mathbf{p}(G) = \{(H, R) \in \mathbf{F}(o) : S \subset H \text{ and } R \subset I^\circ\}.$$

For each $(a, b) \in \mathbf{K}$ we let

$$\mathbf{P}^{(a,b)}(G) = \{F \in \mathbf{F}(o) : F^{(a,b)} \in \mathbf{p}(G)\}.$$

Proposition. Suppose $F, G \in \mathbf{F}o$ and $(a, b) \in \mathbf{K}^+$. Then

$$F \in \mathbf{n}(G) \Leftrightarrow F^{(a,b)} \in \mathbf{n}(G^{(a,b)}).$$

Proof. The point here is that if $S \in \mathbf{R}(o)$ and H is a halfplane containing o then $S \subset H$ if and only if $S^\circ \subset H^\circ$. \square

Proposition. Suppose $G \in \mathbf{F}(o)$. Then

$$\{\{G^{(a,b)}\} : (a, b) \in \mathbf{K}\} \cup \{\mathbf{p}^{(a,b)} : (a, b) \in \mathbf{K}\}$$

has eight members and is a partition of $\mathbf{F}(o)$.

Theorem. Suppose L_1, L_2, L_3 are three distinct lines; $H_i \in \mathbf{H}(L_i)$, $i = 1, 2, 3$; $L_1 \cap L_2 \cap L_3 \neq \emptyset$;

$$L_1 \cap H_2 \cap H_3 \neq \emptyset \quad \text{and} \quad L_2 \cap H_2 \cap H_3^\circ \neq \emptyset.$$

Then

$$L_3 \cap H_1 \cap H_2 \neq \emptyset.$$

Proof. Let $a_1 \in L_1 \cap H_2 \cap H_3$ and let $a_2 \in L_2 \cap H_2 \cap H_3^\circ$. Then $\mathbf{s}(a_1, a_2)$ is a subset of $H_1 \cap H_2$ and meets L_3 in a point a_3 . Since $\mathbf{s}(a_1, a_3) \subset \mathbf{s}(a_1, a_2) \subset H_1$ we infer that $a_3 \in H_1$. since $\mathbf{s}(a_2, a_3) \subset \mathbf{s}(a_1, a_2) \subset H_2$ we infer that $a_3 \in H_2$. \square

Definition. For each $G \in \mathbf{F}(o)$ we let

$$\mathbf{o}^+(G) = \{G^{(1,1)}\} \cup \{G^{(-1,-1)}\} \cup \mathbf{p}^{(1,1)} \cup \mathbf{p}^{(-1,-1)}$$

and we let

$$\mathbf{o}^-(G) = \{G^{(1,-1)}\} \cup \{G^{(-1,1)}\} \cup \mathbf{p}^{(1,-1)} \cup \mathbf{p}^{(-1,1)}$$

If $F, G \in \mathbf{F}(o)$ we write

$$F \sim_{\mathbf{o}} G$$

and say F has the same orientation as G if $F \in \mathbf{o}^+(G)$ and we write

$$F \not\sim_{\mathbf{o}} G$$

and say F has the opposite orientation to G if $F \in \mathbf{o}^-(G)$

Theorem. Suppose $F, G \in \mathbf{F}(o)$. Then

$$F \sim_{\mathbf{o}} G \Leftrightarrow F^\circ \sim_{\mathbf{o}} G^\circ.$$

Proof. Simple exercise for the reader. \square

Theorem. Then $\sim_{\mathbf{o}}$ is a equivalence relation on $\mathbf{F}(o)$. corresponding to which there are exactly two equivalence classes.

Furthermore, if $G \in \mathbf{F}(o)$ then $\mathbf{o}^+(G)$ and $\mathbf{o}^-(G)$ are the equivalence classes for $\sim_{\mathbf{o}}$.

Proof. Suppose (H_i, R_i) , $i = 1, 2, 3$, are flags. We need to show that

$$(1) \quad (H_1, R_1) \sim_{\mathbf{o}} (H_1, R_1);$$

$$(2) \quad (H_2, R_2) \sim_{\mathbf{o}} (H_1, R_1) \Rightarrow (H_2, R_2) \sim_{\mathbf{o}} (H_1, R_1);$$

$$(3) \quad (H_2, R_2) \sim_{\mathbf{o}} (H_1, R_1) \text{ and } (H_3, R_3) \sim_{\mathbf{o}} (H_2, R_2) \Rightarrow (H_3, R_3) \sim_{\mathbf{o}} (H_1, R_1).$$

That (1) and (2) hold is obvious.

Let us prove (3). Suppose $(H_1, R_1) \in \mathbf{o}^+((H_2, R_2))$ and $(H_2, R_2) \in \mathbf{o}^+((H_3, R_3))$ but $(H_1, R_1) \in \mathbf{o}^-((H_3, R_3))$. Then

$$R_1 \subset H_2 \cap H_3; \quad R_2 \subset H_1^\circ \cap H_3; \quad R_3 \subset H_2^\circ \cap H_1.$$

Then $L_1 \cap H_3 \cap H_2 \neq \emptyset$ and $L_3 \cap H_1 \cap H_2^\circ \neq \emptyset$ so the Lemma gives $L_2 \cap H_3 \cap H_1 \neq \emptyset$ which is incompatible with $R_2 \subset H_1^\circ \cap H_3$.

Definition. Suppose $\tau \in \mathcal{B}(o)$. We say a τ is **orientation preserving** if $(\tau[H], \tau[R]) \sim_{\mathbf{o}} (H, R)$ for any $(H, R) \in \mathbf{F}(o)$. We say a τ is **orientation reversing** if $(\tau[H], \tau[R]) \not\sim_{\mathbf{o}} (H, R)$ for any $(H, R) \in \mathbf{F}(o)$.

Theorem. Any member of $\mathcal{B}(o)$ is either orientation preserving or orientation reversing. Furthermore, if $\sigma, \tau \in \mathcal{B}(o)$ then $\tau \circ \sigma$ is orientation preserving if and only if σ and τ are both orientation preserving or orientation reversing.