

## Math 218D Problem Session: Week 8

October 21, 2022

### 1. Gram-Schmidt and QR

The purpose of the Gram–Schmidt process is to replace a basis  $\{v_1, \dots, v_k\}$  of a subspace  $V$  of  $\mathbf{R}^n$  with an **orthogonal basis** of  $V$  (a basis whose vectors are an orthogonal set).

The vectors  $v_1 = (1, 2, -2)$ ,  $v_2 = (1, 1, 1)$  form a basis for a plane  $V$  in  $\mathbf{R}^3$ . Set

$$\begin{aligned}u_1 &= v_1 \\u_2 &= v_2 - \frac{u_1 \cdot v_2}{u_1 \cdot u_1} u_1.\end{aligned}$$

These two vectors are the output of the Gram–Schmidt process.

a) Compute  $\frac{u_1}{\|u_1\|}$  and  $\frac{u_2}{\|u_2\|}$ , and confirm that  $\left\{\frac{u_1}{\|u_1\|}, \frac{u_2}{\|u_2\|}\right\}$  is an orthonormal set of vectors (you need to compute 3 dot products).

b) We can find the QR decomposition of  $A = \begin{pmatrix} 1 & 1 \\ 2 & 1 \\ -2 & 1 \end{pmatrix}$  by setting

$$Q = \begin{pmatrix} \left| \frac{u_1}{\|u_1\|} \right. & \left| \frac{u_2}{\|u_2\|} \right. \\ \left. \frac{u_1}{\|u_1\|} \right. & \left. \frac{u_2}{\|u_2\|} \right. \\ \left. \frac{u_1}{\|u_1\|} \right. & \left. \frac{u_2}{\|u_2\|} \right. \end{pmatrix}.$$

Then  $A = QR$  for some upper-triangular matrix  $R$ , and you saw a formula for  $R$  in lecture. Here is another way to find  $R$ :

$$R = Q^T A.$$

Use this to compute  $R$ , and confirm that  $A = QR$  by multiplying  $Q$  times  $R$ .

**Note:** The method of finding  $R$  given in lecture is much faster, as it involves only book-keeping your work from finding  $Q$ .

- c) Explain why this formula for  $R$  worked, i.e. why  $A = QR$  had to imply that  $Q^T A = R$ .
- d) Explain how you could compute the projection matrix  $P_V$  using  $Q$ . (You do not need to do the computation.)
- e) Find the least-squares solution of  $Ax = (1, 1, 0)$  using  $R\hat{x} = Q^T b$ .

## 2. Another Gram–Schmidt

a) Apply the Gram–Schmidt process to the vectors

$$v_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \quad v_2 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \quad v_3 = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$$

to obtain an orthogonal set  $\{u_1, u_2, u_3\}$ .

b) Find the  $QR$  decomposition of  $A = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix}$ .

c) Consider the vector  $b = (1, 1, 1)$ . Since  $\{u_1, u_2, u_3\}$  is a basis for  $\mathbf{R}^3$ , there are scalars  $x_1, x_2, x_3$  such that  $b = x_1u_1 + x_2u_2 + x_3u_3$ . Solve for these scalars by taking the dot product of this equation with each of  $u_1, u_2, u_3$ , giving 3 equations

$$b \cdot u_i = (x_1u_1 + x_2u_2 + x_3u_3) \cdot u_i \quad \text{for } i = 1, 2, 3.$$

(These equations simplify dramatically when you compute the dot products.)

d) Explain how you could instead solve for these scalars using the formula  $QQ^T = P_{\mathbf{R}^3} = I_3$ .

**Hint:** Note that  $b = Q(Q^T b)$ .

### 3. Some quick determinants

Compute the determinants of the following matrices:

$$\mathbf{a)} \begin{pmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 1 & 2 & 3 \end{pmatrix} \quad \mathbf{b)} \begin{pmatrix} 1 & 10 & 17 \\ 0 & 2 & \pi \\ 0 & 0 & 3 \end{pmatrix} \quad \mathbf{c)} \begin{pmatrix} 1 & 0 \\ 0 & 5 \end{pmatrix}$$

$$\mathbf{d)} \begin{pmatrix} 0 & 1 \\ 5 & 0 \end{pmatrix} \quad \mathbf{e)} \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \quad \mathbf{f)} \begin{pmatrix} 0 & 0 & 2 \\ 3 & 0 & 0 \\ 0 & 4 & 0 \end{pmatrix}$$

$$\mathbf{g)} \begin{pmatrix} 1 & 0 & 0 \\ 7 & 3 & 0 \\ 5 & 5 & 1 \end{pmatrix} \cdot \begin{pmatrix} 2 & 2 & 2 \\ 0 & 3 & -1 \\ 0 & 0 & 1 \end{pmatrix} \quad \mathbf{h)} \begin{pmatrix} 2 & 5 \\ 1 & 2 \end{pmatrix}^{20}$$

**4. Some determinants with variables**

a) Compute the determinant of each of  $A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$ ,  $A^2$ ,  $A^{-1}$ , and  $A - xI_2$ . Find the two values of  $x$  so that  $\det(A - xI_2) = 0$ .

b) Compute the determinant of

$$\begin{pmatrix} 1-x & 1 & 1 \\ 2 & 2-x & 2 \\ 1 & 2 & 3-x \end{pmatrix}.$$

This is a polynomial in the variable  $x$ —what degree is the polynomial?

## 5. Signs of determinants

We gave a geometric interpretation of the absolute value of a determinant in lecture. In this problem we will investigate what the *sign* of a determinant means geometrically. (The *sign* of a number is  $+1$  if the number is positive and  $-1$  if it is negative.)

- a) Draw the vectors  $u = (1, -1)$ ,  $v = (2, 3)$ . Is  $v$  clockwise or counterclockwise from  $u$ ? What is the *sign* of the determinant of  $\begin{pmatrix} 1 & -1 \\ 2 & 3 \end{pmatrix}$ ?
- b) Draw the vectors  $u = (-1, 2)$ ,  $v = (1, 1)$ . Is  $v$  clockwise or counterclockwise from  $u$ ? What is the *sign* of the determinant of  $\begin{pmatrix} -1 & 2 \\ 1 & 1 \end{pmatrix}$ ?

Let  $u, v, w$  be vectors in  $\mathbf{R}^3$ . With your right hand, point your index finger in the direction of  $u$ , your middle finger in the direction of  $v$ , and your thumb in the direction of  $w$ . We say that  $u, v, w$  are in *right-hand order* if, when you point your thumb at your face, your middle finger is counterclockwise of your index finger. Otherwise, the vectors are in *left-hand order*.

- c) Are the vectors  $u = (0, 1, 0)$ ,  $v = (1, 1, 0)$ ,  $w = (1, 1, 1)$  in right-hand order or left-hand order?
- d) Are the vectors  $u = (1, 1, 0)$ ,  $v = (0, 1, 0)$ ,  $w = (1, 1, 1)$  in right-hand order or left-hand order?
- e) What is the sign of the determinants of

$$\begin{pmatrix} 0 & 1 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix} \quad \text{and} \quad \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix}?$$

- f) What do you think the sign of the  $3 \times 3$  determinant has to do with right-hand order?