

Math 218D-1: Homework #8

due Wednesday, October 26, at 11:59pm

1. a) Let $v, w \in \mathbf{R}^n$. Show that

$$\|v + w\|^2 = \|v\|^2 + \|w\|^2$$

if $v \perp w$.

- b) Let V be a subspace of \mathbf{R}^n , let $b \in \mathbf{R}^n$, and let $v \in V$. Use a) and the fact that $b - b_V \in V^\perp$ to show that

$$\|b - v\|^2 = \|b - b_V\|^2 + \|b_V - v\|^2.$$

Use this to prove that b_V really is the closest vector in V to b .

- c) Let V be a subspace of \mathbf{R}^n and let $b \in \mathbf{R}^n$. Use a) to show that $\|b_V\| \leq \|b\|$, with equality if and only if $b \in V$.

2. For each set of vectors, decide if they are orthogonal, orthonormal, or neither; then compute $Q^T Q$, where Q is the matrix with the vectors as columns.

a) $\left\{ \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}, \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix} \right\}$ b) $\left\{ \frac{1}{2} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \frac{1}{2} \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}, \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 0 \\ 1 \\ -1 \end{pmatrix} \right\}$

c) $\left\{ \frac{1}{3} \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix}, \frac{1}{3} \begin{pmatrix} -2 \\ 1 \\ 2 \end{pmatrix} \right\}$ d) $\left\{ \frac{1}{3} \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix}, \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}, \frac{1}{\sqrt{18}} \begin{pmatrix} -4 \\ 1 \\ 1 \end{pmatrix} \right\}$

3. The following subspaces V are given as the span of an *orthogonal* set of vectors. For each subspace V and vector b , compute the orthogonal projection b_V using the *projection formula*, and compute the projection matrix P_V using the *outer product formula*.

$$\text{a) } V = \text{Span} \left\{ \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 2 \\ -2 \\ 1 \end{pmatrix} \right\} \quad b = \begin{pmatrix} 3 \\ 8 \\ 1 \end{pmatrix}$$

$$\text{b) } V = \text{Span} \left\{ \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 1 \\ -1 \end{pmatrix} \right\} \quad b = \begin{pmatrix} 0 \\ 3 \\ 6 \end{pmatrix}$$

$$\text{c) } V = \text{Span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ -1 \\ -1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \\ 1 \\ -1 \end{pmatrix} \right\} \quad b = \begin{pmatrix} 4 \\ 2 \\ -4 \\ 2 \end{pmatrix}$$

$$\text{d) } V = \text{Span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\} \quad b = \begin{pmatrix} 7 \\ -3 \\ 2 \end{pmatrix}$$

$$\text{e) } V = \text{Span} \left\{ \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}, \begin{pmatrix} -4 \\ 1 \\ 1 \end{pmatrix} \right\} \quad b = \begin{pmatrix} 9 \\ -2 \\ 3 \end{pmatrix}$$

4. For each subspace V of Problem 3, scale the spanning vectors to find an *orthonormal* basis of V , and (re)compute the projection matrix P_V using the formula $P_V = QQ^T$. (Your answers should be exact, in terms of square roots.)
5. Suppose that $\{u_1, u_2, \dots, u_n\}$ is an orthonormal basis of \mathbf{R}^n . Use the outer product formula to explain why

$$I_n = u_1 u_1^T + u_2 u_2^T + \cdots + u_n u_n^T.$$

6. Give an example of each of the following, or explain why no such example exists.
- A matrix Q with orthonormal columns, but $QQ^T \neq I_n$.
 - Two nonzero orthogonal vectors that are linearly dependent.
 - An orthonormal basis for the plane $x + y + z = 0$.

7. Use the Gram–Schmidt process to find orthogonal bases of the following subspaces.

$$\begin{array}{ll} \text{a) } \text{Span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix} \right\} & \text{b) } \text{Span} \left\{ \begin{pmatrix} 1 \\ -1 \\ 2 \\ -2 \end{pmatrix}, \begin{pmatrix} 1 \\ -3 \\ 2 \\ -1 \end{pmatrix}, \begin{pmatrix} 2 \\ 2 \\ 4 \\ -1 \end{pmatrix} \right\} \\ \text{c) } \text{Span} \left\{ \begin{pmatrix} 1 \\ -2 \\ 3 \end{pmatrix}, \begin{pmatrix} 2 \\ -5 \\ 1 \end{pmatrix}, \begin{pmatrix} -1 \\ 5 \\ 12 \end{pmatrix} \right\} & \text{d) } \text{Nul} \begin{pmatrix} 1 & 2 & -1 & 4 \\ 3 & 6 & -3 & 12 \end{pmatrix} \end{array}$$

8. Consider the subspace $V = \text{Col}(A)$, where

$$A = \begin{pmatrix} 1 & 1 & 2 \\ -1 & -3 & 2 \\ 2 & 2 & 4 \\ -2 & -1 & -1 \end{pmatrix}.$$

Find an orthonormal basis $\{u_1, u_2, u_3, u_4\}$ of \mathbf{R}^4 such that $\{u_1, u_2, u_3\}$ is a basis for V . Your answer should be exact, in terms of square roots.

9. Consider the plane

$$V = \text{Span} \left\{ \begin{pmatrix} 1 \\ -1 \\ 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ -1 \\ 1 \end{pmatrix} \right\}$$

and the vector

$$v = \begin{pmatrix} 4 \\ -1 \\ 3 \\ 3 \end{pmatrix} = 2 \begin{pmatrix} 1 \\ -1 \\ 2 \\ 1 \end{pmatrix} + \begin{pmatrix} 2 \\ 1 \\ -1 \\ 1 \end{pmatrix} \in V.$$

Find all vectors **contained in** V that are orthogonal to v .

10. For each of the following matrices A and vectors b , find the QR decomposition of A , and find the least-squares solution of $Ax = b$ by back-substitution in $R\hat{x} = Q^T b$. Your answers should be exact, in terms of square roots.

$$\text{a) } A = \begin{pmatrix} 1 & 1 \\ 1 & 0 \\ 0 & 2 \end{pmatrix}, b = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \quad \text{b) } A = \begin{pmatrix} 1 & 1 & 2 \\ -1 & -3 & 2 \\ 2 & 2 & 4 \\ -2 & -1 & -1 \end{pmatrix}, b = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

11. In this problem, we use a *QR* decomposition to *quickly* compute the best-fit parabola with specified y -values at $x = -2, -1, 1, 2$, as in HW7#3.

a) Compute the matrix A such that the least squares solution of $A(C, D, E) = (b_1, b_2, b_3, b_4)$ gives the coefficients of the parabola $y = Cx^2 + Dx + E$ that best fits the data points $(-2, b_1), (-1, b_2), (1, b_3), (2, b_4)$. (Presumably you computed this in HW7#3.)

b) Find the *QR* decomposition of A .

c) Find the best-fit parabola through the points $(-2, 3), (-1, -1), (1, 1), (2, 3)$ by back-substitution in $R\hat{x} = Q^T b$. You should get the same answer as in HW7#3.

Note that we can now repeat part c) with new y -values in $O(n^2)$ time.

12. Recall that an *orthogonal* matrix is a square matrix with *orthonormal* columns.

a) If Q is an orthogonal matrix, show that Q^{-1} is orthogonal.

b) If Q_1 and Q_2 are orthogonal matrices of the same size, show that $Q_1 Q_2$ is orthogonal.

c) If Q is orthogonal, show that $\det(Q) = \pm 1$.

13. Decide if each statement is true or false, and explain why.

a) A matrix with orthogonal columns has full row rank.

b) If $\{v_1, \dots, v_n\}$ is a linearly independent set of vectors, then it is orthogonal.

c) If $\{v_1, v_2\}$ is a basis for a plane V , then for any vector b ,

$$b_V = \frac{b \cdot v_1}{v_1 \cdot v_1} v_1 + \frac{b \cdot v_2}{v_2 \cdot v_2} v_2.$$

d) If Q has orthonormal columns, then the distance from x to y equals the distance from Qx to Qy .

e) If $A = QR$ is a *QR*-factorization of a matrix A , then the rows of Q form an orthonormal basis for $\text{Row}(A)$.

14. Compute the determinants of the following matrices *using Gaussian elimination*.

a) $\begin{pmatrix} -2 & 1 \\ 1 & 3 \end{pmatrix}$ b) $\begin{pmatrix} -3 & 3 & 2 \\ 3 & 0 & 0 \\ -9 & 18 & 7 \end{pmatrix}$

c) $\begin{pmatrix} -4 & -3 & -3 & -2 \\ 4 & 1 & 2 & -2 \\ -12 & -3 & -9 & 3 \\ 0 & 8 & 19 & 33 \end{pmatrix}$ d) $\begin{pmatrix} 2 & 2 & -1 \\ -4 & -5 & 5 \\ 6 & 1 & 12 \end{pmatrix}$

15. Suppose that

$$\det \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix} = 10.$$

Find the determinants of the following matrices.

$$\begin{array}{lll} \text{a)} \begin{pmatrix} d & e & f \\ a & b & c \\ g & h & i \end{pmatrix} & \text{b)} \begin{pmatrix} a & b & c \\ d & e & f \\ g+2d & h+2e & i+2f \end{pmatrix} & \text{c)} \begin{pmatrix} a & b & c \\ \frac{1}{2}d & \frac{1}{2}e & \frac{1}{2}f \\ g & h & i \end{pmatrix} \\ \text{d)} \begin{pmatrix} g & h & i \\ a & b & c \\ d & e & f \end{pmatrix} & \text{e)} \begin{pmatrix} a & b & c \\ d & e & f \\ 2g+d & 2h+e & 2i+f \end{pmatrix} & \text{f)} \begin{pmatrix} a & d & g \\ b & e & h \\ c & f & i \end{pmatrix} \\ \text{g)} 2 \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix} & \text{h)} \begin{pmatrix} a & d & g \\ b & e & h \\ c & f & i \end{pmatrix} \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix} & \text{i)} \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}^{-1} \\ \text{j)} - \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix} & \text{k)} \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}^3 & \text{l)} \begin{pmatrix} a & b+2c & c \\ d & e+2f & f \\ g & h+2i & i \end{pmatrix} \end{array}$$

16. Find $\det(E)$ when:

- E is the elementary matrix for a row replacement.
- E is the elementary matrix for $R_i \times c$.
- E is the elementary matrix for a row swap.

17. A matrix A has the $PA = LU$ factorization

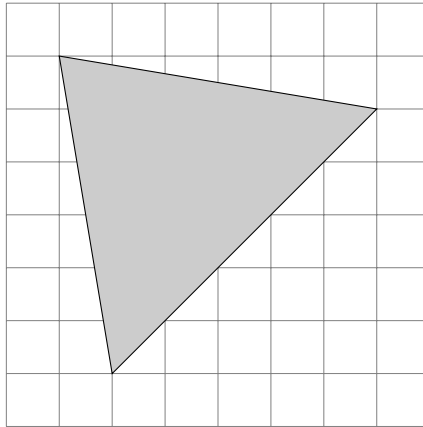
$$\begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} A = L \begin{pmatrix} 2 & 1 & 3 & 0 \\ 0 & -1 & 1 & 5 \\ 0 & 0 & 4 & 7 \\ 0 & 0 & 0 & -3 \end{pmatrix}.$$

What is $\det(A)$?

18. Let V be a subspace of \mathbf{R}^n and let P_V be the projection matrix onto V .

- Find $\det(P_V)$ when $V \neq \mathbf{R}^n$.
- Find $\det(P_V)$ when $V = \mathbf{R}^n$.

- 19.** Let A be an $n \times n$ matrix with columns v_1, v_2, \dots, v_n .
- Show that if $\{v_1, v_2, \dots, v_n\}$ is orthogonal then $|\det(A)| = \|v_1\| \|v_2\| \cdots \|v_n\|$.
[Hint: Compute $A^T A$ and its determinant.]
 - Suppose that A is invertible. Show that $|\det(A)| \leq \|v_1\| \|v_2\| \cdots \|v_n\|$, with equality if and only if the set $\{v_1, v_2, \dots, v_n\}$ is orthogonal.
[Hint: Use Problem 1(c) and the QR decomposition of A .]
- 20.** Compute the area of the triangle pictured below using a 2×2 determinant. (The grid marks are one unit apart.)



- 21.** Decide if each statement is true or false, and explain why.
- $\det(A + B) = \det(A) + \det(B)$.
 - $\det(ABC^{-1}) = \frac{\det(A)\det(B)}{\det(C)}$.
 - $\det(AB) = \det(BA)$.
 - $\det(3A) = 3 \det(A)$.
 - If A^5 is invertible then A is invertible.
 - The determinant of A is the product of its diagonal entries.
 - If the columns of A are linearly dependent, then $\det(A) = 0$.
 - If A is a 3×3 matrix with determinant zero, then two of the columns of A are scalar multiples of each other.