GEOMETRY AND MEASURE ON $CAT(\kappa)$ SPACES

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1. $CAT(\kappa)$ spaces

For more on $CAT(\kappa)$ spaces, consult a metric geometry text, such as [\[BBI01\]](#page-4-0).

Definition 1.1 (Injectivity radius). For any $\kappa \in \mathbb{R}$, a model space of curvature κ is a Riemannian manifold M_{κ} with geodesic distance \mathbf{d}_{κ} and constant curvature κ . The injectivity radius of M_{κ} is $R_{\kappa} = \pi/\sqrt{\kappa}$ when $\kappa > 0$ and $R_{\kappa} = \infty$ if $\kappa < 0$.

Definition 1.2 (Comparison triangle). Given a triangle $\triangle xyz$ (a union of geodesics x to y to z to x) in a metric space (M, d) , a *comparison triangle* of $\triangle xyz$ in a model space $(M_{\kappa}, \mathbf{d}_{\kappa})$ is a triangle $\triangle x'y'z'$ in M_{κ} such that $\{x', y', z'\}$ is an isometric copy of $\{x, y, z\}$.

Definition 1.3 (CAT(κ) metric space). A metric space (\mathcal{M}, d) is CAT(κ) if

- 1. any two points $x, y \in M$ such that $\mathbf{d}(x, y) < R_{\kappa}$ can be joined by a unique geodesic of length $\mathbf{d}(x, y)$; and
- 2. for any triangle $\triangle xyz$ in M with $\mathbf{d}(x, y) + \mathbf{d}(y, z) + \mathbf{d}(z, x) < 2R_{\kappa}$, if $\triangle x'y'z'$ is a comparison triangle in M_{κ} of $\triangle xyz$, then the constant-speed geodesics γ : $[0,1] \to \mathcal{M}$ from y to z and $\gamma' : [0,1] \to M_{\kappa}$ from y' to z' satisfy, for all $t \in [0,1]$,

$$
\mathbf{d}\big(x,\gamma(t)\big)\leq \mathbf{d}_{\kappa}\big(x',\gamma'(t)\big).
$$

Example 1.4.

Remark 1.5. The definition of $CAT(\kappa)$ space is never used directly in these lectures. The developments instead rest on certain consequences.

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Definition 1.6. The *angle* between geodesics $\gamma_i : [0, \varepsilon_i) \to M$ for $i = 1, 2$ emanating from $\bar{\mu}$ in a CAT(κ) space (\mathcal{M}, d) and parametrized by arclength is characterized by

$$
\cos(\angle(\gamma_1, \gamma_2)) = \lim_{t,s \to 0} \frac{s^2 + t^2 - \mathbf{d}^2(\gamma_1(s), \gamma_2(t))}{2st}.
$$

The geodesics γ_i are *equivalent* if the angle between them is 0. The set $S_{\bar{\mu}}\mathcal{M}$ of equivalence classes is the *space of directions* at $\bar{\mu}$.

Remark 1.7. Definition [1.6](#page-1-0) introduces angle by taking the law of cosines by fiat, namely $s^2 + t^2 = d^2 + 2st \cos(\angle)$.

Lemma 1.8. The notion of angle makes the space $S_{\bar{\mu}}\mathcal{M}$ of directions into a length space whose angular metric \mathbf{d}_s satisfies

$$
\mathbf{d}_s(V,W) = \angle(V,W) \text{ whenever } V,W \in S_{\bar{\mu}}\mathcal{M} \text{ with } \angle(V,W) < \pi
$$

Proof. This is [\[MMT23a,](#page-4-1) Proposition 1.7], which in turn is [\[BBI01,](#page-4-0) Lemma 9.1.39]. \square

Definition 1.9. The tangent cone at a point $\bar{\mu}$ in a CAT(κ) space M is

 $T_{\bar{\mu}}\mathcal{M} = S_{\bar{\mu}}\mathcal{M} \times [0,\infty) / (S_{\bar{\mu}}\mathcal{M} \times \{0\}),$

whose apex is often also called $\bar{\mu}$ (although it can be called $\mathcal O$ if necessary for clarity). The length of a vector $W = W_{\bar{\mu}} \times t$ with $W_{\bar{\mu}} \in S_{\bar{\mu}}M$ is $||W|| = t$ in $T_{\bar{\mu}}M$. The unit tangent sphere $S_{\bar{\mu}}\mathcal{M}$ of length 1 vectors in $T_{\bar{\mu}}\mathcal{M}$ is identified with the space of directions.

Example 1.10.

1. three quadrants:

2. kale: see slides for many pictures

3. open book: see slides for many pictures

Definition 1.11. Given tangent vectors $V, W \in T_{\bar{\mu}}\mathcal{M}$, their angular pairing is

$$
\langle V, W \rangle_{\bar{\mu}} = ||V|| ||W|| \cos(\angle(V, W)).
$$

The subscript $\bar{\mu}$ is suppressed when the point $\bar{\mu}$ is clear from context.

Lemma 1.12. For a fixed basepoint in a CAT (κ) space, the angular pairing function $\langle \cdot , \cdot \rangle_{\bar{\mu}} : T_{\bar{\mu}}\mathcal{M} \times T_{\bar{\mu}}\mathcal{M} \to \mathbb{R}$ is continuous.

Proof. This is [\[MMT23a,](#page-4-1) Lemma 1.21], where it is derived from Lemma [1.8.](#page-1-1) \Box

The angular metric \mathbf{d}_s induces a metric on the tangent cone $T_{\bar{\mu}}\mathcal{M}$ which makes $T_{\bar{\mu}}\mathcal{M}$ into a length space.

Definition 1.13. The *conical metric* on the tangent cone $T_{\bar{\mu}}\mathcal{M}$ of a CAT(κ) space is

$$
\mathbf{d}_{\bar{\mu}}(V,W)=\sqrt{\|V\|^2+\|W\|^2-2\langle V,W\rangle} \ \ \text{for}\ V,W\in T_{\bar{\mu}}\mathcal{M}.
$$

Lemma 1.14 ([\[BBI01,](#page-4-0) Lemma 3.6.15]). Any geodesic triangle in $T_{\bar{\mu}}\mathcal{M}$ with one vertex at the apex is isometric to a triangle in \mathbb{R}^2 .

Definition 1.15. Fix a point $\bar{\mu}$ in a CAT(κ) space (\mathcal{M}, d). For each point v in the set $\mathcal{M}' \subseteq \mathcal{M}$ of points with a unique shortest path to $\bar{\mu}$, write γ_v for the unit-speed shortest path from $\bar{\mu}$ to v and $V = \gamma'_i$ $v'_v(0)$ for its tangent vector at $\bar{\mu}$. Define the *log map* by

$$
\log_{\bar{\mu}} : \mathcal{M}' \to T_{\bar{\mu}} \mathcal{M}
$$

$$
v \mapsto \mathbf{d}(\bar{\mu}, v)V.
$$

M is conical with apex $\bar{\mu}$ if $\mathcal{M}' = \mathcal{M}$ and $\log_{\bar{\mu}} : \mathcal{M} \to T_{\bar{\mu}}\mathcal{M}$ is an isometry.

2. MEASURES ON $CAT(\kappa)$ SPACES

Definition 2.1 (Localized measure). A measure μ on CAT(κ) M is localized if

- μ has unique Fréchet mean $\bar{\mu}$,
- μ has locally convex Fréchet function in a neighborhood of $\bar{\mu}$, and
- the logarithm map $\log_{\bar{\mu}} : \mathcal{M} \to T_{\bar{\mu}}\mathcal{M}$ is μ -almost surely uniquely defined.

Denote the pushforward of a localized measure μ to $T_{\bar{\mu}}\mathcal{M}$ by

$$
\widehat{\mu} = (\log_{\bar{\mu}})_{\sharp} \mu.
$$

Example 2.2. Intuition behind Definition [2.1](#page-2-0) is that μ should be "Fréchet-localized", in the sense that "retracting" to the tangent cone at $\bar{\mu}$ captures all of the mass. For instance, if μ is a measure on a CAT(κ) space M that is supported in a metric ball $B(\bar{\mu}, R_{\mu})$ of radius $R_{\mu} < \frac{1}{2}R_{\kappa} = \pi/(2\sqrt{\kappa})$ —this can be any measure when $\kappa = 0$ —then μ is localized. Indeed, thanks to results by Kuwae [\[Kuw14\]](#page-4-2), the Fréchet mean $\bar{\mu}$ of such a measure is unique and the Fréchet function of μ is k-uniform convex in a small ball around $\bar{\mu}$. In addition, such a measure is retractable because the cut locus (the closure of the set of points with more than shortest path to $\bar{\mu}$) has measure 0.

Definition 2.3. Fix a localized measure μ on a CAT(κ) space M. The Fréchet function F has directional derivative at $\bar{\mu}$ given by

$$
\nabla_{\bar{\mu}} F : T_{\bar{\mu}} \mathcal{M} \to \mathbb{R}
$$

$$
V \mapsto \frac{d}{dt} F(\exp_{\bar{\mu}} tV)|_{t=0}
$$

in which the exponential is a geodesic with constant speed and tangent V at $\bar{\mu}$.

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The next three concepts are [\[MMT23b,](#page-4-3) Definition 2.12, 2.17, and 2.18], where explanations of their background, geometry, and motivation can be found.

Definition 2.4 (Escape cone). The *escape cone* of a localized measure μ on a CAT(κ) space $\mathcal M$ is the set E_μ of tangent vectors along which the directional derivative of the Fréchet function vanishes at $\bar{\mu}$:

$$
E_{\mu} = \{ X \in T_{\bar{\mu}} \mathcal{M} \mid \nabla_{\bar{\mu}} F(X) = 0 \}.
$$

Proposition 2.5. If μ is a measure on a CAT(κ) space M, then the escape cone E_{μ} is a closed, path-connected, geodesically convex subcone of $(T_{\bar{\mu}}\mathcal{M}, \mathbf{d}_{\bar{\mu}})$.

Definition 2.6 (Hull). If X is a conical CAT(0) space, then the hull of any subset $S \subseteq \mathcal{X}$ is the smallest geodesically convex cone hull $S \subseteq \mathcal{X}$ containing S. For a localized measure μ on a CAT(κ) space M, set

hull
$$
\mu =
$$
hull supp $(\widehat{\mu})$,

the hull of the support in $\mathcal{X} = T_{\bar{\mu}}\mathcal{M}$ of the pushforward measure $\widehat{\mu} = (\log_{\bar{\mu}})_{\sharp} \mu$.

Definition 2.7 (Fluctuating cone). The *fluctuating cone* of a localized measure μ on a CAT(κ) space M is the intersection

$$
C_{\mu} = E_{\mu} \cap \text{hull } \mu
$$

= {V \in \text{hull } \mu | \nabla_{\bar{\mu}} F(V) = 0}

of the escape cone and hull of μ . Let \overline{C}_{μ} be the closure in $T_{\overline{\mu}}\mathcal{M}$ of the escape cone C_{μ} .

Remark 2.8. The purpose of the fluctuating cone C_μ is to encapsulate those directions in which the Fréchet mean $\bar{\mu}$ can be induced to wiggle by adding to μ a point mass in M along that direction (this is made precise in the main theorem of [\[MMT23d,](#page-4-4) Section 4); hence the terminology. However, if the measure μ is supported on a "thin" subset of M , then it is possible to induce fluctuations in directions that have nothing whatsoever to do with the geometry in $\mathcal M$ of the (support of) μ by adding a point mass outside supp μ ; see the next Example. That is why the fluctuating cone is assumed to lie within the convex hull of the support of $\hat{\mu}$: only fluctuations of $\bar{\mu}$ that can be realized—at least in principle—by means of samples from μ itself are relevant to the asymptotics in a central limit theorem.

Example 2.9. For a concrete example, consider a measure μ supported on the spine R of an open book $\mathcal M$ (see [\[HHL](#page-4-5)⁺13]). The spine R is simply a vector space, where the usual central limit theorem yields convergence to a Gaussian supported on R. It is true that the Fréchet mean $\bar{\mu}$ can be induced to fluctuate off of R onto any desired page of M by adding a point mass on the relevant page, but that observation is irrelevant to the CLT, which only cares about fluctuations of $\bar{\mu}$ within R.

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