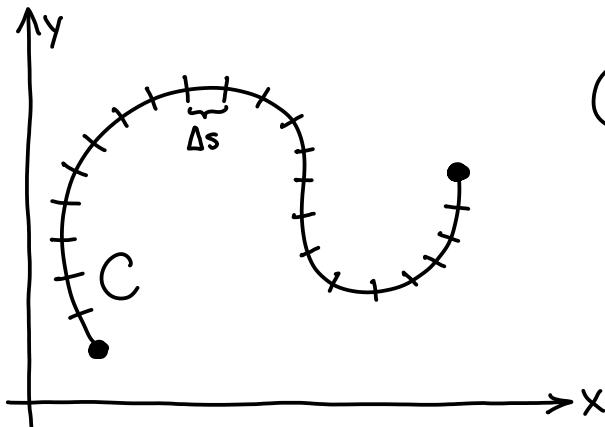


6.1-Scalar and Vector Line Integrals

Until now, domains have been the same dimension as the space they lived in.

What if our domain is a curve (1-d) in the plane (2-d) or in space (3-d)?

What would a Riemann sum look like?



$$Q = \lim_{i} \sum f(x_i, y_i) \Delta s$$

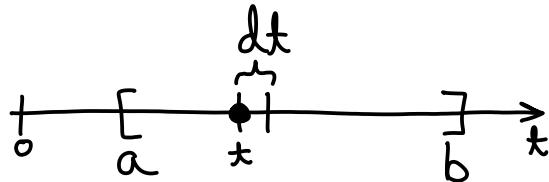
density (Q/length)

$$= \int_C f(x, y) ds \quad \xrightarrow{\text{scalar line integral}}$$

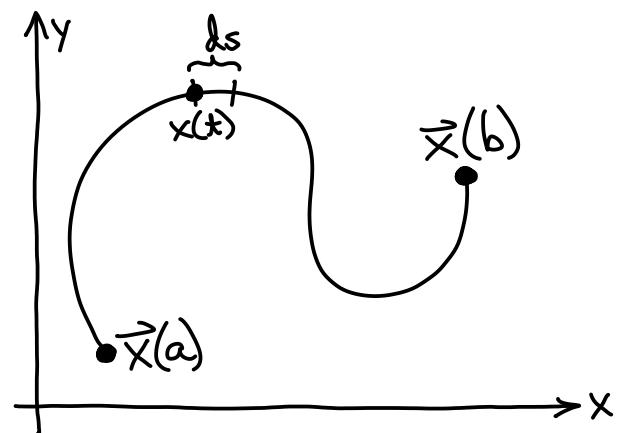
As with change of variables, these are undesirable domains.
So let's

- ① View as images
- ② Use pull back / stretching factor approach.

parametrization!



\vec{x}



We already know that $ds = \|\vec{x}'(t)\| dt$, so

$$\int_C f(\vec{x}) ds = \int_a^b f(\vec{x}(t)) \|\vec{x}'(t)\| dt$$

stretching factor

Handy fact: The above integral is independent of the parametrization. So, use whatever is most convenient!

Ex: An irregular wire follows the curve parametrized by $\vec{x}(t) = (t, t^2)$, $t \in [0, 1]$, with $S = x + y$.

Compute the mass, center of mass, and m.o.i. around the x-axis.

All of these are done with the same stretching factor!

$$\vec{x}' = (1, 2t), \text{ so s.f.} = \|\vec{x}'\| = \sqrt{1+4t^2}.$$

$$m = \int_C dm$$

$$= \int_C S ds$$

$$= \int_0^1 (x+y) \|\vec{x}'\| dt$$

$$= \int_0^1 (t+t^2) \sqrt{1+4t^2} dt$$

$$\bar{x} = \frac{1}{m} \int_C x dm$$

$$= \frac{1}{m} \int_C x S ds$$

$$= \frac{1}{m} \int_0^1 x(x+y) \|\vec{x}'\| dt$$

$$= \frac{1}{m} \int_0^1 (t)(t+t^2) \sqrt{1+4t^2} dt$$

$$I = \int_C r^2 dm$$

$$= \int_C r^2 S ds$$

$$= \int_0^1 (y)^2 (x+y) \|\vec{x}'\| dt$$

$$= \int_0^1 (t^2)^2 (t+t^2) \sqrt{1+4t^2} dt$$

$$\bar{y} = \frac{1}{m} \int_C y dm$$

$$= \frac{1}{m} \int_C y S ds$$

$$= \frac{1}{m} \int_0^1 y(x+y) \|\vec{x}'\| dt$$

$$= \frac{1}{m} \int_0^1 (t^2)(t+t^2) \sqrt{1+4t^2} dt$$

Ex: A fence sits on the unit circle, with $h(x,y) = \frac{x+2}{5}$. What is the area of the fence?

$$A = \int_C dA = \int_C h(\vec{x}) ds$$

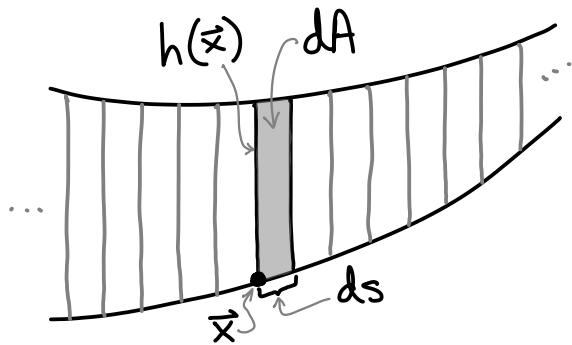


Diagram illustrating the parametrization of the unit circle:

A horizontal line segment from 0 to 2π is mapped by an arrow to a unit circle in the $x-y$ plane.

Let $\vec{x}(t) = (x, y)$ where $x = \cos t$, $y = \sin t$

$\vec{x}'(t) = (-\sin t, \cos t)$

$\|\vec{x}'(t)\| = 1$

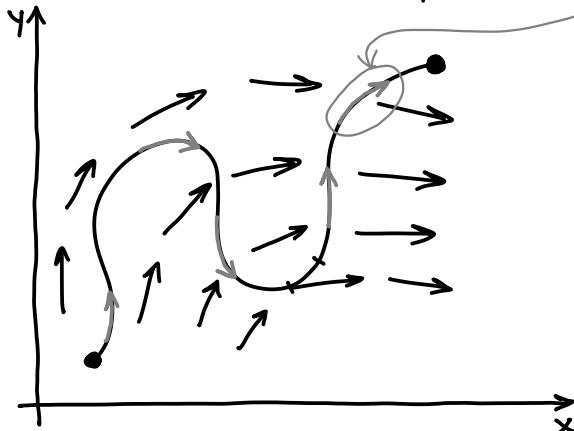
$$= \int_0^{2\pi} \left(\frac{x+2}{5} \right) \| \vec{x}' \| dt$$

$$= \int_0^{2\pi} \left(\frac{\cos t + 2}{5} \right) (1) dt$$

Recall $W = \vec{F} \cdot \vec{d}$. This assumes :

① \vec{F} is constant ; ② \vec{d} is over a straight path.

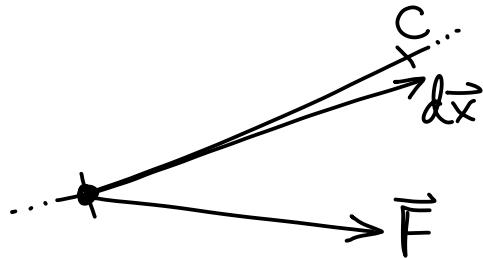
But what if they aren't ?



Let C be an oriented curve

Chop the curve into pieces !

- ① Each piece is ~straight
- ② Force is ~constant

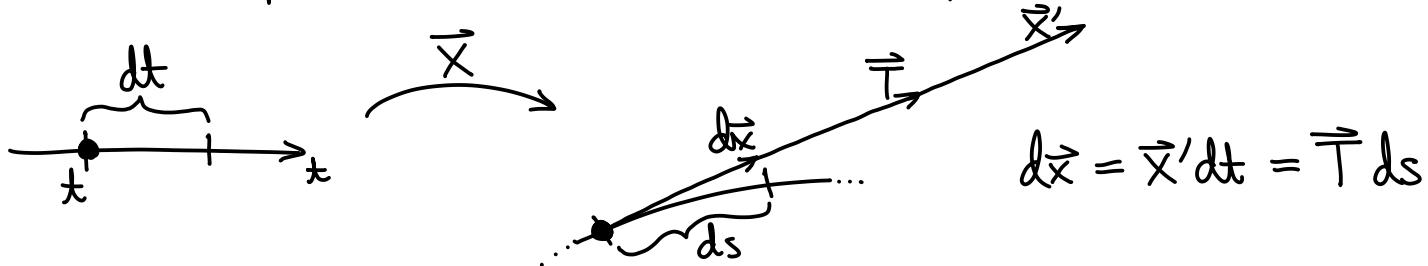


On each piece, $dW = \vec{F} \cdot d\vec{x}$

Adding up over all pieces we get

$$W = \int_C dW = \int_C \vec{F} \cdot d\vec{x} \quad \text{vector line integral}$$

With a parametrization we already know



so we can rewrite as $\int_C \vec{F} \cdot d\vec{x} = \int_a^b \vec{F} \cdot \vec{x}' dt = \int_C \vec{F} \cdot \vec{T} ds$

Ex: Wind exerts force on you of $\vec{F}(x,y) = (y, -x)$. How much work does it take you to walk CCW along the top half of the unit circle?

① You push with force $-\vec{F}$ to oppose the wind. So

$$W = \int_C (-\vec{F}) \cdot d\vec{x}$$

② Parametrize the curve by

$$\vec{x} = \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \cos t \\ \sin t \end{pmatrix}, t \in [0, \pi] \quad \Rightarrow \quad \vec{x}' = \begin{pmatrix} -\sin t \\ \cos t \end{pmatrix}$$

③ Compute:

$$\begin{aligned} W &= \int_C -\vec{F} \cdot d\vec{x} = \int_0^\pi -\vec{F} \cdot \vec{x}' dt \\ &= \int_0^\pi -\begin{pmatrix} y \\ -x \end{pmatrix} \cdot \vec{x}' dt \\ &= \int_0^\pi -\begin{pmatrix} \sin t \\ -\cos t \end{pmatrix} \cdot \begin{pmatrix} -\sin t \\ \cos t \end{pmatrix} dt = \int_0^\pi 1 dt = \pi \end{aligned}$$

Handy fact: $\int_a^b \vec{F} \cdot \vec{x}' dt$ gives the same value as long as $\vec{x}(t)$ has the correct orientation. But...

Key point:

The parametrization has to go the same direction as the orientation!

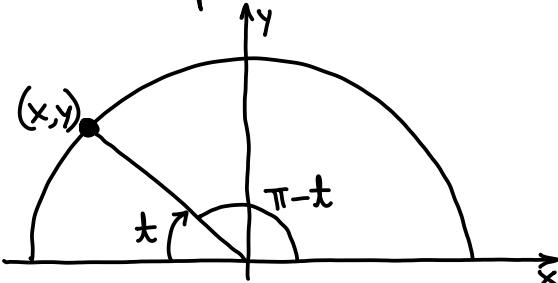
Otherwise your $d\vec{x}$ is backwards, a.k.a. off by $\cdot(-1)$!

Def: Given an oriented curve C from \vec{a} to \vec{b} , the curve C^- moves along the same path with the opposite orientation, from \vec{b} to \vec{a} .

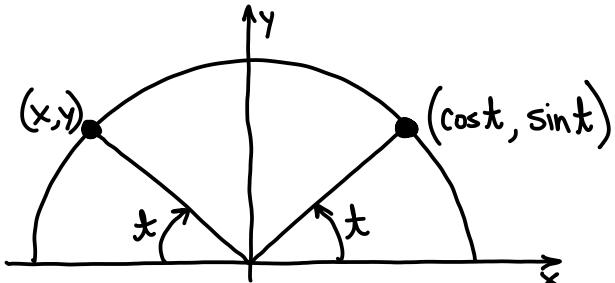
Thm: $\int_{C^-} \vec{F} \cdot d\vec{x} = - \int_C \vec{F} \cdot d\vec{x}$

So if you parametrize C the wrong way, your result will be wrong by $\cdot(-1)$.

Ex: Same as previous, what if walking cw?
How to parametrize?



$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \cos(\pi - t) \\ \sin(\pi - t) \end{pmatrix} = \begin{pmatrix} -\cos t \\ \sin t \end{pmatrix}$$



$$\begin{pmatrix} x \\ y \end{pmatrix} = R \begin{pmatrix} \cos t \\ \sin t \end{pmatrix} = \begin{pmatrix} -\cos t \\ \sin t \end{pmatrix}$$

Then $W = \int_{C_2} (-\vec{F}) \cdot d\vec{x} = \dots = -\pi$

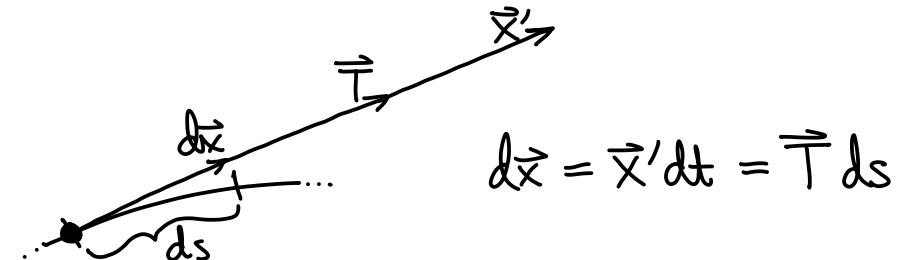
Alt: This is the same curve as previous with the opposite orientation. So

$$\int_{C_2} = \int_{C^-} = -\int_C = -\pi$$

We have seen that if \vec{F} represents forces, then $\int_C \vec{F} \cdot d\vec{x}$ represents work.

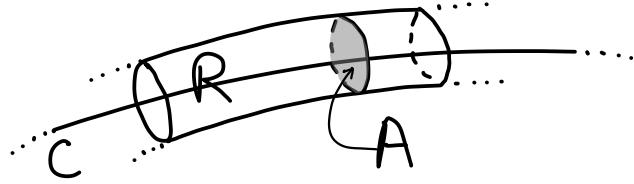
What if \vec{F} represents a fluid flow (as velocity)?

Recall:

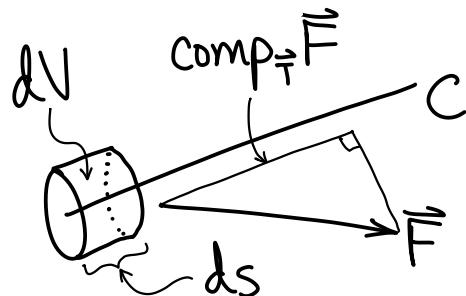


$$\int_C \vec{F} \cdot d\vec{x} = \int_a^b \vec{F} \cdot \vec{x}' dt = \int_C \vec{F} \cdot \vec{T} ds$$

Consider a thin region R around C, with section area A.



What is the total rate Q that the fluid in R is flowing along C?

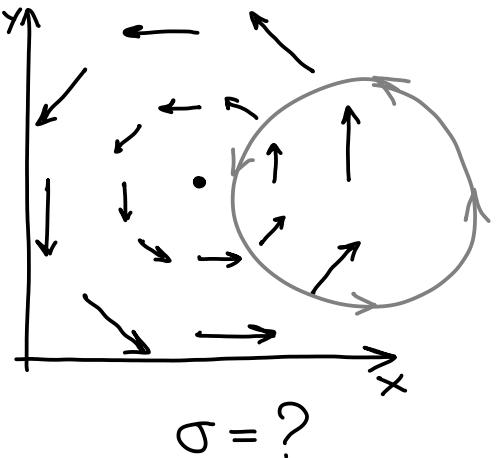
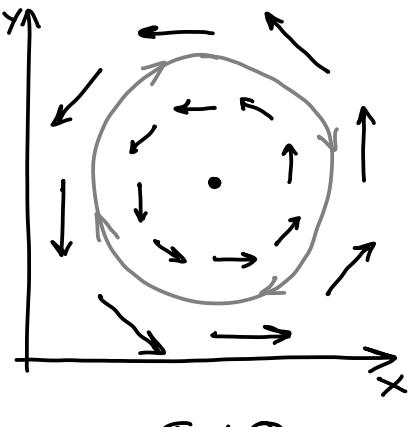
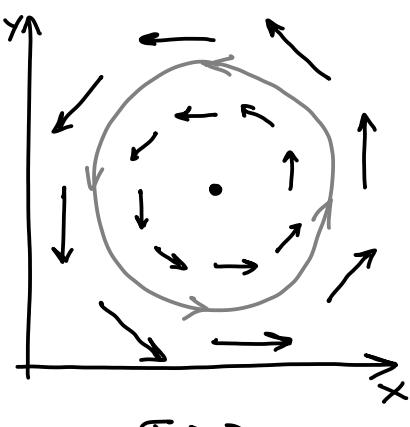


$$dQ = (\text{comp}_T \vec{F}) dV \\ = (\vec{F} \cdot \vec{T})(A ds)$$

$$Q = \int_C dQ = A \int_C \vec{F} \cdot \vec{T} ds = A \int_C \vec{F} \cdot d\vec{x}$$

So $\int_C \vec{F} \cdot d\vec{x}$ represents the rate (per section area) of fluid flowing along C.

For a closed curve (starts/ends at same point), $\int_C \vec{F} \cdot d\vec{x}$ is called the circulation (σ) of \vec{F} along C.



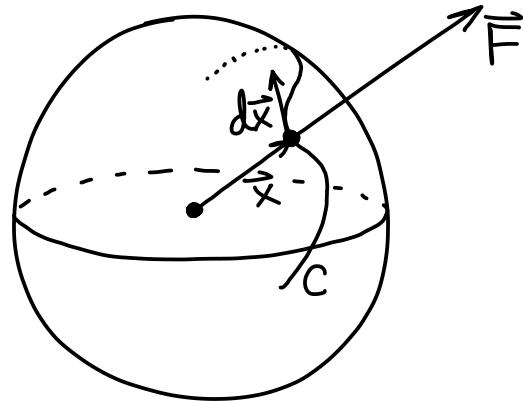
For small objects, circulation suggests how the fluid would rotate it.

Look out for fortunate geometry!

Ex: C is parametrized by $\rho=1$, $\phi=t \sin t$, $\theta=t^2 e^t$ for $t \in [0,1]$, and $\vec{F} = x^2 y \vec{x}$. Compute $\int_C \vec{F} \cdot d\vec{x}$.

Notice:

- \vec{x} is on sphere $\rho=1$, so $d\vec{x}$ is always \parallel to sphere
 - $\vec{F} \parallel \vec{x}$ is always \perp to sphere
- $$\Rightarrow \vec{F} \cdot d\vec{x} = 0 \Rightarrow \int_C \vec{F} \cdot d\vec{x} = 0.$$



Coordinate line integrals

Recall $d\vec{x} = \vec{x}' dt = \begin{pmatrix} x' \\ y' \\ z' \end{pmatrix} dt$

It is reasonable to rewrite this as

$$= \begin{pmatrix} x' dt \\ y' dt \\ z' dt \end{pmatrix} = \begin{pmatrix} dx \\ dy \\ dz \end{pmatrix}$$

With $\vec{F} = (P, Q, R)$ then, we write

$$\int_C \vec{F} \cdot d\vec{x} = \int_C \begin{pmatrix} P \\ Q \\ R \end{pmatrix} \cdot \begin{pmatrix} dx \\ dy \\ dz \end{pmatrix} = \int_C P dx + Q dy + R dz$$

This notation:

- Relates to "differential forms" (Ch. 8).
Natural & powerful — but beyond this course!
- In common use.

Symmetry theorems

For scalar line integrals, it's just what you would expect:

Thm: If ① f is odd over L

② C is symmetric over L

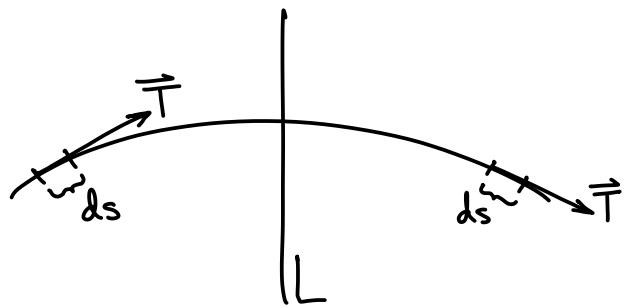
then $\int_C f \, ds = 0$

NB - Both conditions must hold!

Must use the same line for each!

But for vector line integrals $\int_C \vec{F} \cdot d\vec{x} = \int_C \vec{F} \cdot \vec{T} \, ds$,
odd symmetry does not work!

(On corresponding pieces
of curve, the ds 's are
equal — but the \vec{T} 's
are neither equal nor opposite...)

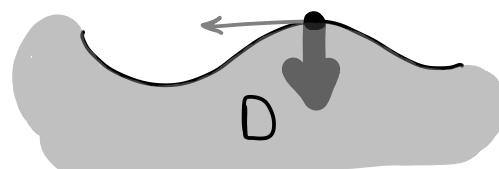
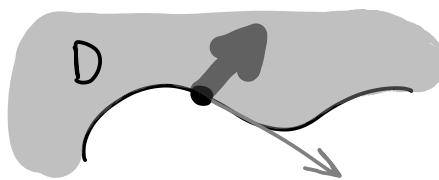


6.2 - Green's Theorem

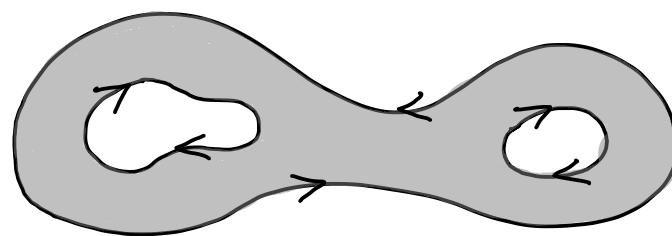
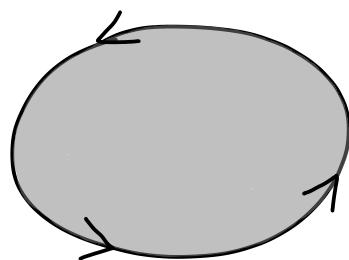
Boundary

We now view boundary as an oriented thing.

The boundary curve ∂D of a region $D \subset \mathbb{R}^2$ is oriented such that D is "on the left".



This means that on outside boundary curves the orientation of ∂D is ccw — but not for inside!



Accumulation

Say D is divided into pieces D_1, D_2 .



The mass in D is the sum of the masses in D_1, D_2 . We say mass "accumulates over D ", or is an "accumulating quantity".

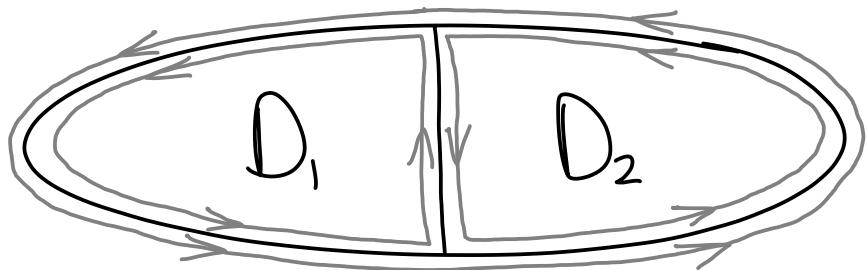
Perimeter does not accumulate over areas!

Tempting to say accumulation is a feature of physical/concrete quantities, not geometric/algebraic ones.

But — given a vector field \vec{F} on D ,

boundary circulation accumulates!

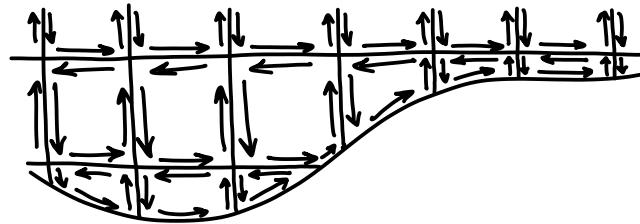
$\int_{\partial D_1} \vec{F} \cdot d\vec{x}$, $\int_{\partial D_2} \vec{F} \cdot d\vec{x}$ both go over shared edge, but with opposite orientations which then cancel!



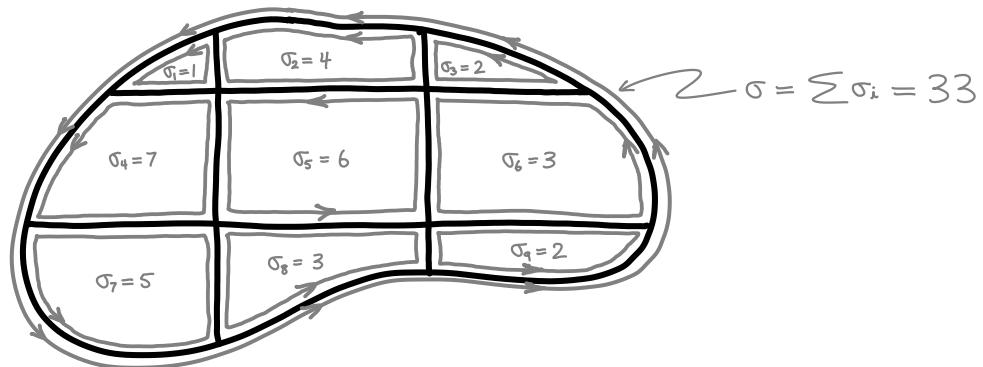
So

$$\int_{\partial D_1} \vec{F} \cdot d\vec{x} + \int_{\partial D_2} \vec{F} \cdot d\vec{x} = \int_{\partial D} \vec{F} \cdot d\vec{x}$$

Doesn't matter how many pieces!



This accumulation feature allows us a way of thinking of boundary circulation as distributed over the interior, with pieces having locations in the interior.



So, "boundary circulation" behaves like a physical "stuff"!

Density

For mass in a differential area, we have "mass density":



$$dm = \frac{(\text{mass})}{(\text{area})} \cdot dA$$

Similarly, there is a "circulation density"!



$$d\sigma = \frac{\text{bdry. circ.}}{\text{area}} \cdot dA$$

For $\vec{F} = (P, Q)$, circulation density $= \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}$
 $(= \text{"Green's operator"}, \text{grn } \vec{F}, \text{rot } \vec{F}, \text{curl } \vec{F}, (\vec{P} \times \vec{F}) \cdot \vec{k})$

Now consider a domain $D \subset \mathbb{R}^2$ and $\vec{F} = (P, Q)$:

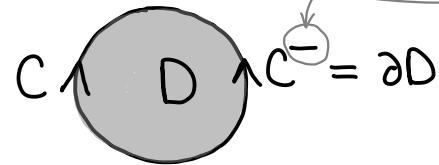
$$\int_{\partial D} \vec{F} \cdot d\vec{x} = \sigma = \iint_D d\sigma = \iint_D (\text{grn } \vec{F}) dA$$

circulation accumulation density

Green's Theorem

Ex: C is the clockwise unit circle, $\vec{F} = (e^x + y, \tan y + 3x)$.
 Compute $\int_C \vec{F} \cdot d\vec{x}$.

Note $C^- = \partial D$ where D is the unit disk. Then

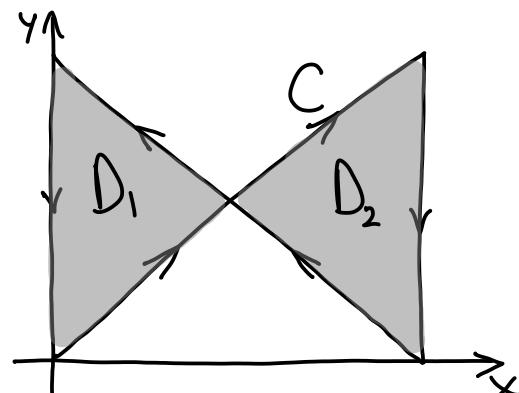


Same curve, but with the opposite orientation

$$\begin{aligned}\int_C \vec{F} \cdot d\vec{x} &= - \int_{C^-} \vec{F} \cdot d\vec{x} = - \int_{\partial D} \vec{F} \cdot d\vec{x} = - \iint_D \text{grn } \vec{F} \, dA \\ &= - \iint_D (3-1) \, dA = -2\pi\end{aligned}$$

Ex: C is made up of line segments from (0,0) to (2,2) to (2,0) to (0,2) to (0,0), and $\vec{F} = (3x-4y, 5x-7y)$.
 Compute $\int_C \vec{F} \cdot d\vec{x}$.

$$C = \partial D_1 + (\partial D_2)^-$$



Then

$$\begin{aligned}\int_C \vec{F} \cdot d\vec{x} &= \int_{\partial D_1} \vec{F} \cdot d\vec{x} + \int_{(\partial D_2)^-} \vec{F} \cdot d\vec{x} \\ &= \int_{\partial D_1} \vec{F} \cdot d\vec{x} - \int_{\partial D_2} \vec{F} \cdot d\vec{x} \\ &= \iint_D \text{grn } \vec{F} \, dA - \iint_{D_2} \text{grn } \vec{F} \, dA \\ &= \iint_D q \, dA - \iint_{D_2} q \, dA \\ &= q(\text{area of } D_1) - q(\text{area of } D_2) = 0\end{aligned}$$

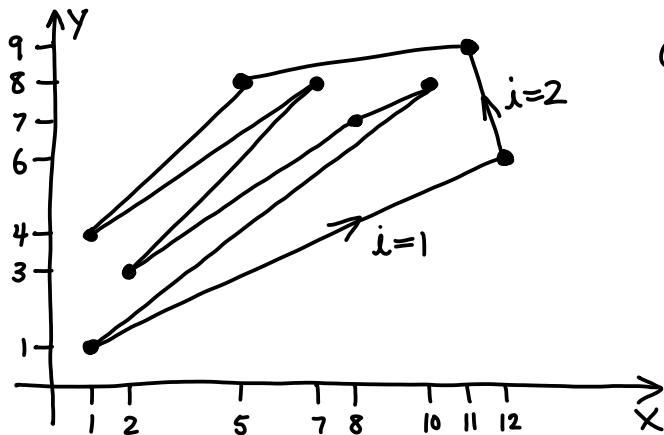
Area

$$\int_{\partial D} \times dy = \int_{\partial D} (0) \cdot d\vec{x} = \iint_D g_{rn}(0) dA = \iint_D 1 dA = \text{area}(D).$$

And for straight line segments (L , from (x_1, y_1) to (x_2, y_2)), you can check that

$$\int_L \times dy = \bar{x} \Delta y \quad \left(= \left(\frac{x_1+x_2}{2}\right)(y_2-y_1)\right)$$

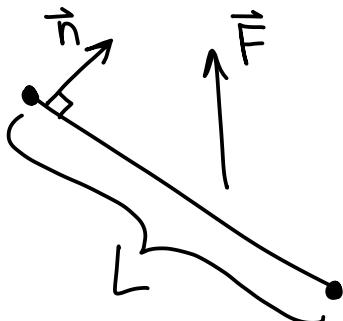
Ex: Compute the area of the polygon below.



$$\begin{aligned} \text{area} &= \int_{\partial D} \times dy = \sum_i \int_{L_i} \times dy \\ \begin{array}{c|c|c|c} i & \bar{x} & \Delta y & \bar{x} \Delta y = \int_{L_i} \times dy \\ \hline 1 & 1\frac{3}{2} & 5 & 6\frac{5}{2} \\ 2 & 2\frac{3}{2} & 3 & 6\frac{9}{2} \\ 3 & 8 & -1 & -8 \\ 4 & 3 & -4 & -12 \\ 5 & 4 & 4 & 16 \\ 6 & 4\frac{1}{2} & -5 & -45\frac{1}{2} \\ 7 & 5\frac{5}{9} & 4 & 20\frac{9}{9} \\ 8 & 6\frac{1}{2} & -7 & -77\frac{1}{2} \end{array} & \left. \begin{array}{l} \sum = \text{area} \\ = 19 \end{array} \right\} \end{aligned}$$

Flux through a curve

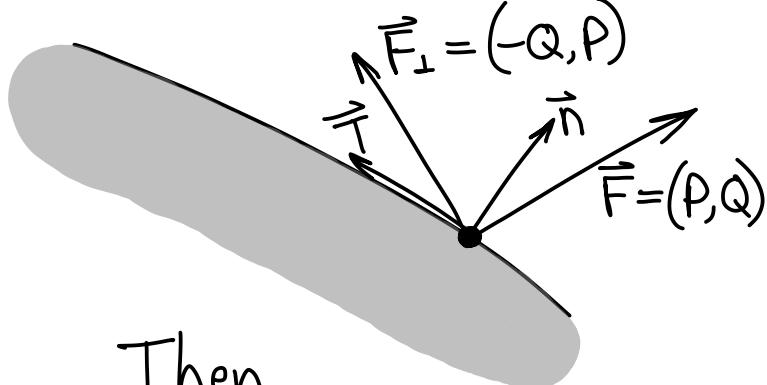
Similar to flux through a surface :



$$\Phi = (\vec{F} \cdot \vec{n}) L$$

Represents flow rate of fluid through L (in \vec{n} direction).

"Boundary flux" on D is flow rate outward across ∂D .



\vec{F}, \vec{n} are 90° rotations of \vec{F}_\perp, \vec{T} (resp.). So

$$\vec{F} \cdot \vec{n} = \vec{F}_\perp \cdot \vec{T}$$

Then

$$\underline{\Phi} = \int_{\partial D} d\underline{\Phi}$$

$$= \int_{\partial D} \vec{F} \cdot \vec{n} \, ds$$

$$= \int_{\partial D} \vec{F}_\perp \cdot \vec{T} \, ds$$

$$= \int_{\partial D} \vec{F}_\perp \cdot d\vec{x}$$

$$\begin{aligned} &= \iint_D \text{grn}(\vec{F}_\perp) \, dA \\ &= \iint_D \frac{\partial(P)}{\partial x} - \frac{\partial(-Q)}{\partial y} \, dA \\ &= \iint_D \left(\frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} \right) \, dA \\ &= \iint_D \nabla \cdot \vec{F} \, dA \end{aligned}$$

2-d divergence theorem

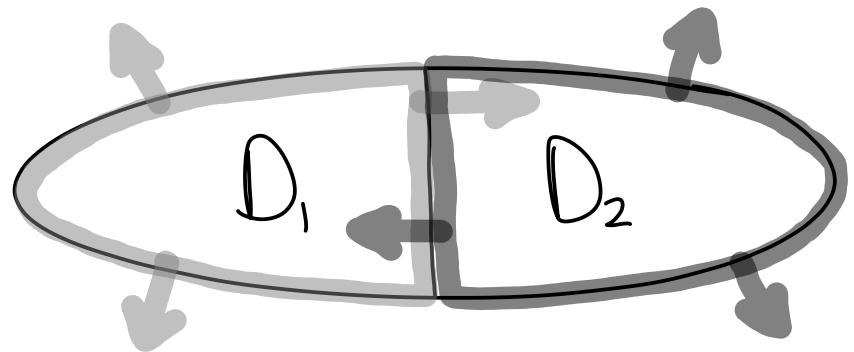
Ex: Compute the flux $\int_C \vec{F} \cdot \vec{n} \, ds$ of $\vec{F} = (2x + e^y, \csc x - 5y)$ outward through the unit circle C .

C is ∂D where D is the unit disk. So

$$\int_C \vec{F} \cdot \vec{n} \, ds = \underline{\Phi} = \iint_D \nabla \cdot \vec{F} \, dA = \iint_D (2 - 5) \, dA = -3(\text{area}) = -3\pi$$

Boundary flux accumulates too!

$\int_{\partial D_1} \vec{F} \cdot \vec{n} ds$, $\int_{\partial D_2} \vec{F} \cdot \vec{n} ds$ both go over shared edge, but with opposite orientations which then cancel!



Alt: on shared edge, any fluid flowing out of D_1 is also flowing into D_2 !

$$\text{So } \int_{\partial D_1} \vec{F} \cdot \vec{n} ds + \int_{\partial D_2} \vec{F} \cdot \vec{n} ds = \int_{\partial D} \vec{F} \cdot \vec{n} ds$$

So we have an interpretation as a density as well.

$$m = \iint_D dm = \iint_D \rho dA \quad \text{mass density}$$

$$\sigma = \iint_D d\sigma = \iint_D g r n \vec{F} dA \quad \text{circulation density}$$

$$\Phi = \iint_D d\Phi = \iint_D \nabla \cdot \vec{F} dA \quad \text{flux density}$$

Comparison to F.T.C.

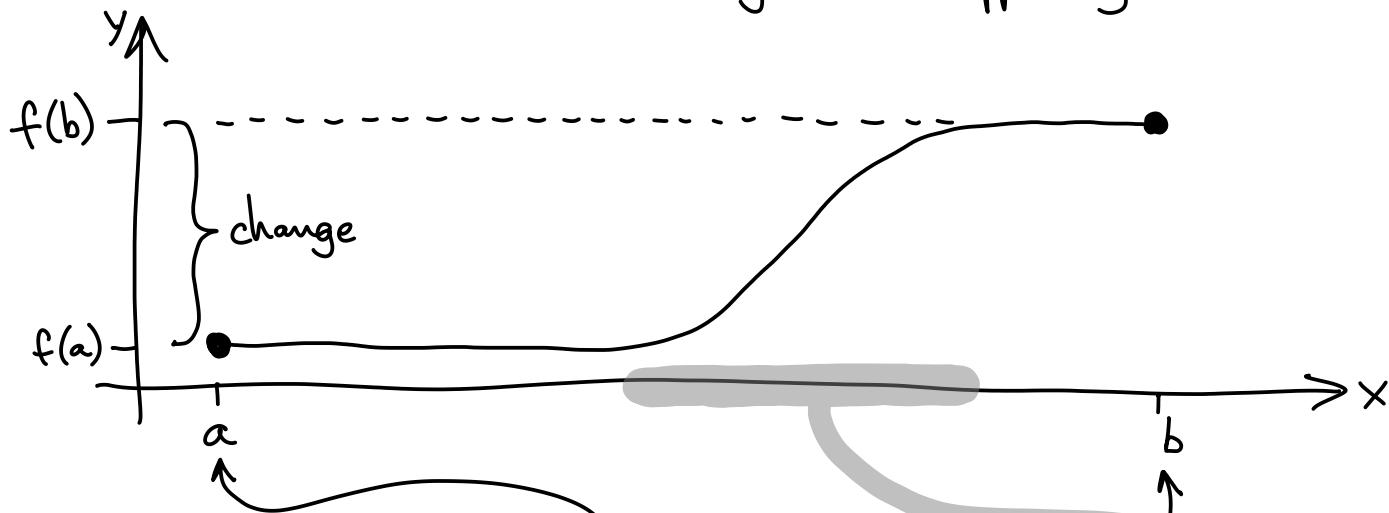
F.T.C. can also be viewed in terms of accumulation/density, viewing $f(x_2) - f(x_1)$ as a quantity called "change" ($= \Delta$). On $I = [a, b]$ then,

$$\Delta \stackrel{\text{def}}{=} \int_I d\Delta = \int_I f' dx$$

change
accumulates
over I

change/size
= change density

The derivative f' is something we can see in a picture, and we know it tells how much change is happening where.



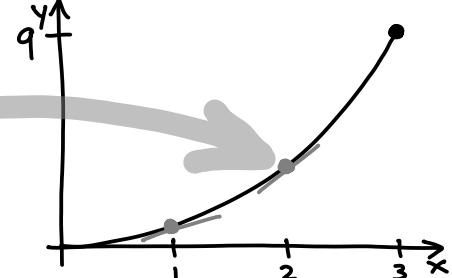
The accumulation of change is measured here...

...but it actually happens here.

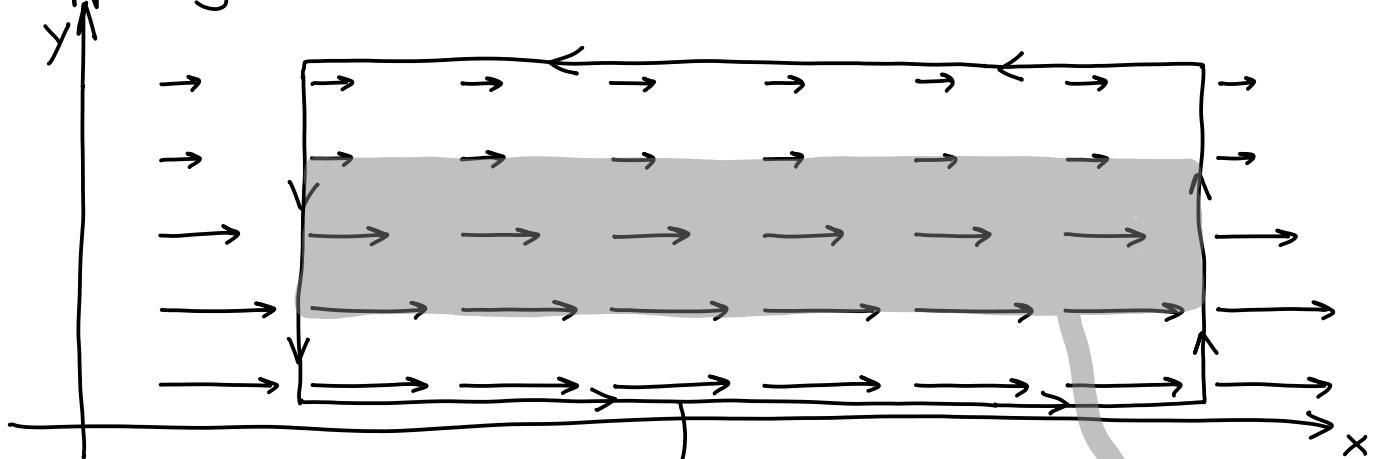
Ex: $f(x) = x^2$ changes by 9 on $[0, 3]$. Is more of this change happening at $x=1$ or at $x=2$?

$$\begin{aligned}f'(x) &= 2x \\f'(1) &= 2 \\f'(2) &= 4\end{aligned}$$

f' = change density
is greater at $x=2$

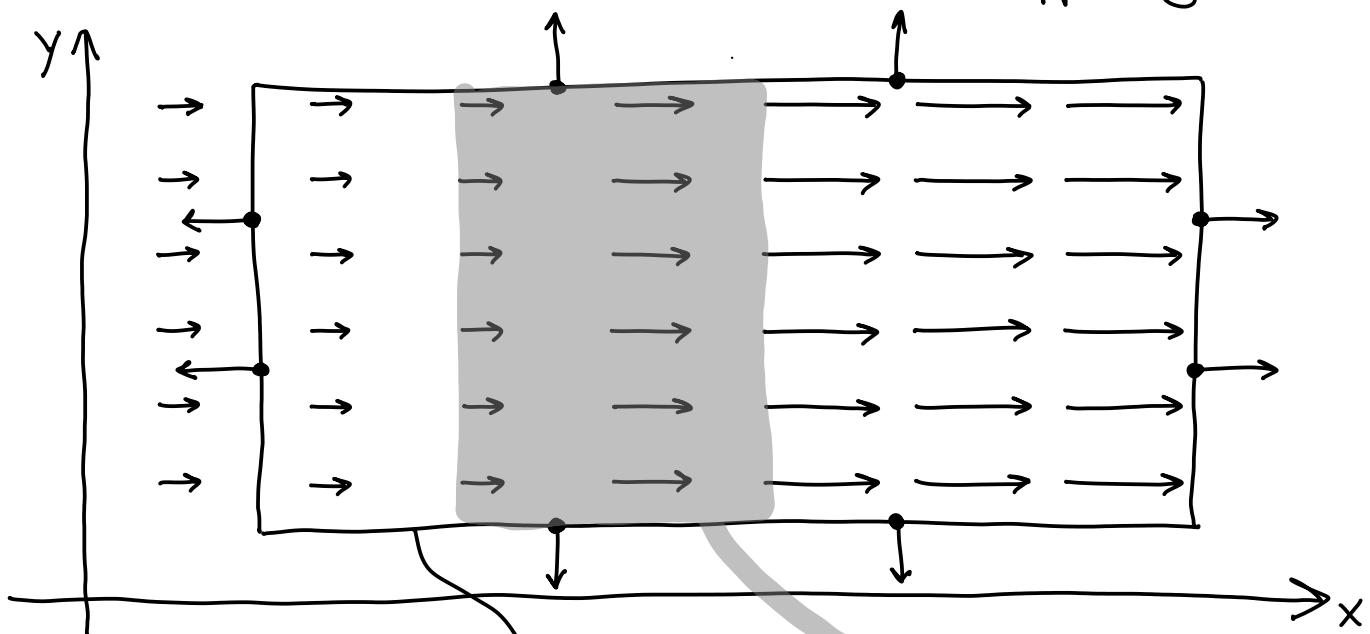


Analogously, $\text{curl } \vec{F}$ tells us how much circulation is happening where.



The accumulation of circulation is measured here but it actually happens here.

And, $\nabla \cdot \vec{F}$ tells us how much flux is happening where.



The accumulation of flux is measured here but it actually happens here.

Ex: $\vec{F} = (2x^2 - 3y^2, 4x + 5y)$ generates a circulation around, and a flux through, the boundary of $[0, 5] \times [1, 6]$. For each of these, is more happening at $(3, 3)$ or $(2, 4)$?

For circulation: $\text{grn } \vec{F} = 4 + 6y$

$$\text{grn } \vec{F}(3, 3) = 22$$

$$\text{grn } \vec{F}(2, 4) = 28$$

$\text{grn } \vec{F} = \text{circ. dens.}$
is greater at $(2, 4)$.

For flux: $\nabla \cdot \vec{F} = 4x + 5$

$$\nabla \cdot \vec{F}(3, 3) = 17$$

$$\nabla \cdot \vec{F}(2, 4) = 13$$

$\nabla \cdot \vec{F} = \text{flux density}$
is greater at $(3, 3)$.

6.3 - Conservative Vector Fields

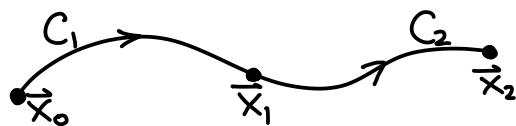
"conservative"

Thm: (Fundamental Theorem of Line Integrals) If $\vec{F} = \nabla f$ is continuous and C starts at A and ends at B , then

$$\int_C \vec{F} \cdot d\vec{x} = f(B) - f(A)$$

This can be seen in terms of accumulation/density!

① The accumulating quantity is "change" (Δ), defined on a path P from \vec{q} to \vec{r} as $\Delta = f(\vec{r}) - f(\vec{q})$.



$$\begin{aligned}\Delta + \Delta_2 &= (f(x_1) - f(x_0)) + (f(x_2) - f(x_1)) \\ &= (f(x_2) - f(x_0)) = \Delta\end{aligned}$$

Ex: Altitude change accumulates along a road.

② The related density is ($\nabla f \cdot \vec{T}$).

The diagram shows a small curved segment of a path. A vector labeled $d\vec{s}$ is shown along the curve, and a vector labeled $d\vec{x}$ is shown tangent to the curve at the same point.

$$d\Delta = \nabla f \cdot d\vec{x} = (\nabla f \cdot \vec{T}) ds$$

Alt: Can view ∇f as the "oriented density", as it relates $d\Delta$ to the "oriented size" $d\vec{x}$.

Then

$$\begin{aligned}\Delta &= \int_C d\Delta = \int_C (\nabla f \cdot \vec{T}) ds \\ &= \int_C \nabla f \cdot d\vec{x}\end{aligned}$$

change density

oriented change density

Ex: $\vec{F} = (2xy^2, 2x^2y)$, $C = \{(cost, sint) \mid t \in [0, \pi]\}$.
Compute $\int_C \vec{F} \cdot d\vec{x}$.

① Note $\vec{F} = \nabla(x^2y^2)$.

② C starts at $A = (1, 0)$ and ends at $B = (-1, 0)$.

Then by F.T.L.I. we have

$$\int_C \vec{F} \cdot d\vec{x} = f(B) - f(A) = 0 - 0 = 0$$

Path independence

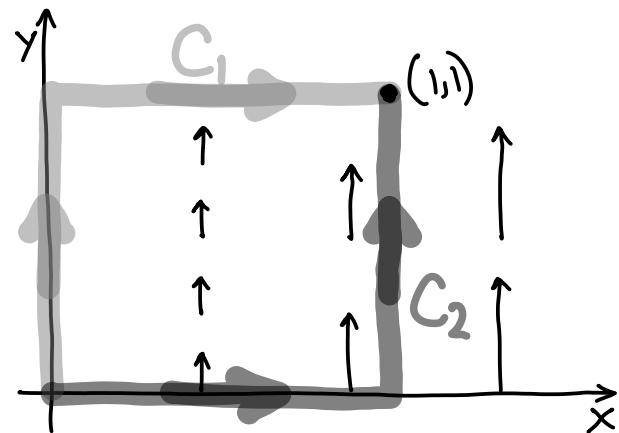
Most line integrals $\int_C \vec{F} \cdot d\vec{x}$ depend heavily on C. Amazingly though, for some vector fields \vec{F} , only the endpoints matter!

Def: \vec{F} "has path independent line integrals" (or, "is path independent") if

$$(C_1, C_2 \text{ share start/end points}) \Rightarrow \left(\int_{C_1} \vec{F} \cdot d\vec{x} = \int_{C_2} \vec{F} \cdot d\vec{x} \right)$$

NB - Most vector fields do not have this property!

Ex: $\vec{F} = (0, x)$, C_1, C_2 as pictured from $(0,0)$ to $(1,1)$.

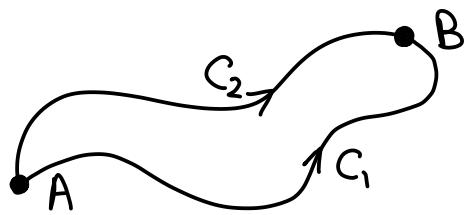


C_1, C_2 start/end at same points.

$\int_{C_1} \vec{F} \cdot d\vec{x}$ is clearly $= 0$.

$\int_{C_2} \vec{F} \cdot d\vec{x}$ is clearly > 0 .

But the F.T.L.I. shows the every (continuous) gradient field $\vec{F} = \nabla f$ is path independent!

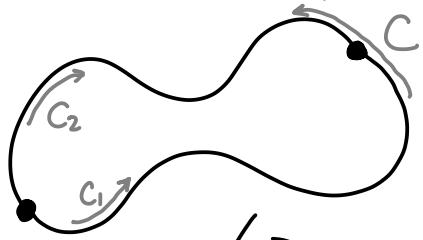


$$\int_{C_1} \vec{F} \cdot d\vec{x} = \int_{C_2} \vec{F} \cdot d\vec{x} = f(B) - f(A)$$

It is also true that every (continuous) path independent vector field is a gradient.

Sketch of proof: Can define $f(\vec{x}) = \int_A^B \vec{F} \cdot d\vec{x}$ (use any path!) then check directly that $\nabla f = \vec{F}$.

Alternative formulation:

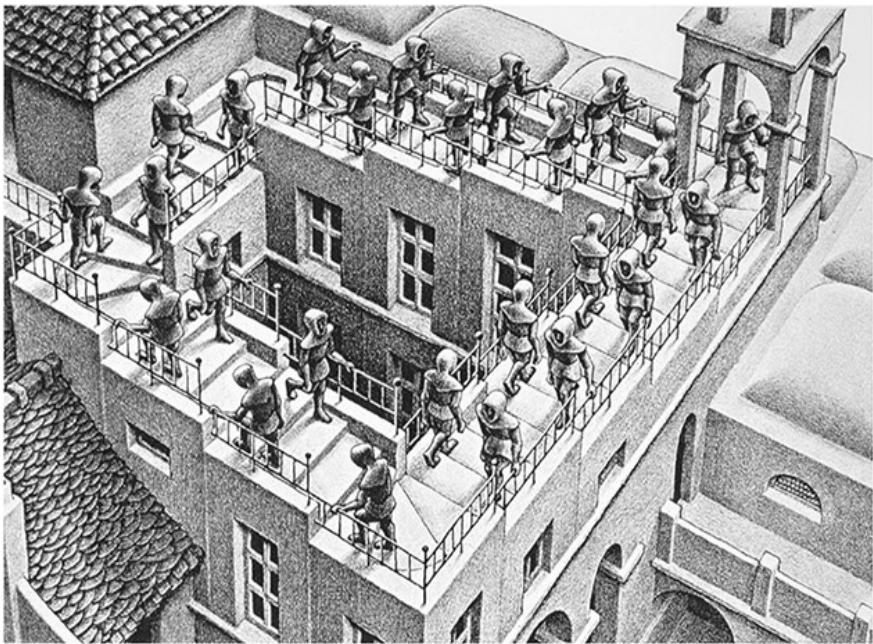


$$\int_{C_1} = \int_{C_2} \Leftrightarrow \int_{C_1} - \int_{C_2} = 0 \Leftrightarrow \int_C = 0$$

$(\vec{F} \text{ is p.i.}) \Leftrightarrow (\text{for all } \text{closed curves}, \oint_C \vec{F} \cdot d\vec{x} = 0)$

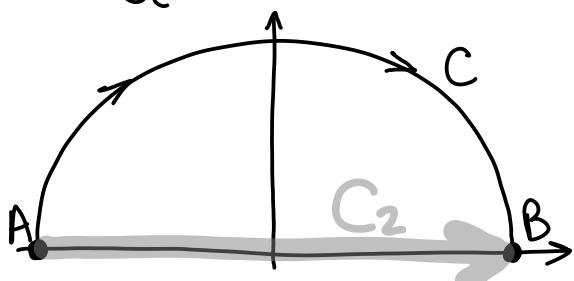
Ex: "Steepness" $= \vec{F} = \nabla h$ is a gradient

$\Leftrightarrow \vec{F}$ is p.i. $\Leftrightarrow \oint_C \vec{F} \cdot d\vec{x} = 0 \Leftrightarrow$ Escher stairs
are impossible!



(P.i. is more useful conceptually than computationally, since $(F \text{ is p.i.}) \Rightarrow (F = \nabla f) \Rightarrow (\text{use F.T.L.I.!})$). But sometimes...

Ex: $\vec{F} = (2xy, x^2)$ p.i., C is top half of unit circle cwise.
Find $\int_C \vec{F} \cdot d\vec{x}$.



\vec{F} is given p.i., so we can choose to use C_2 instead.

$$\vec{x}(t) = (t, 0)$$

$$\int_C \vec{F} \cdot d\vec{x} = \int_{C_2} \begin{pmatrix} 2xy \\ x^2 \end{pmatrix} \cdot \begin{pmatrix} dx \\ 0 \end{pmatrix} = \int_{C_2} \begin{pmatrix} 0 \\ x^2 \end{pmatrix} \cdot \begin{pmatrix} dx \\ 0 \end{pmatrix} = 0.$$

A local test

Thm: For a (C^1) vector field \vec{F} on \mathbb{R}^2 ,
 $(\vec{F} = \nabla f) \iff (\text{grn } \vec{F} = 0)$ irrotational

Pf: $\iff (\vec{F} \text{ p.i.}) \iff (\text{closed } \int_C \vec{F} \cdot d\vec{x} = 0) \iff (\iint_D \text{grn } \vec{F} dA = 0) \iff$ Green's Theorem

Thm: For a (C^1) vector field \vec{F} on \mathbb{R}^3 ,
 $(\vec{F} = \nabla f) \iff (\nabla \times \vec{F} = \vec{0})$

Pf: Similar, but uses a theorem we have not covered yet.

Ex: Is $\vec{F} = (y+3, yz^2+x, yz^2+y)$ a gradient?

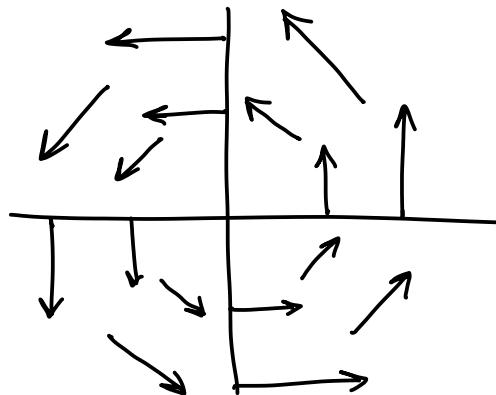
$$\nabla \times \vec{F} = ((z^2+1)-(2yz), \dots, \dots)$$

This already tells us $\nabla \times \vec{F} \neq \vec{0}$, so no.

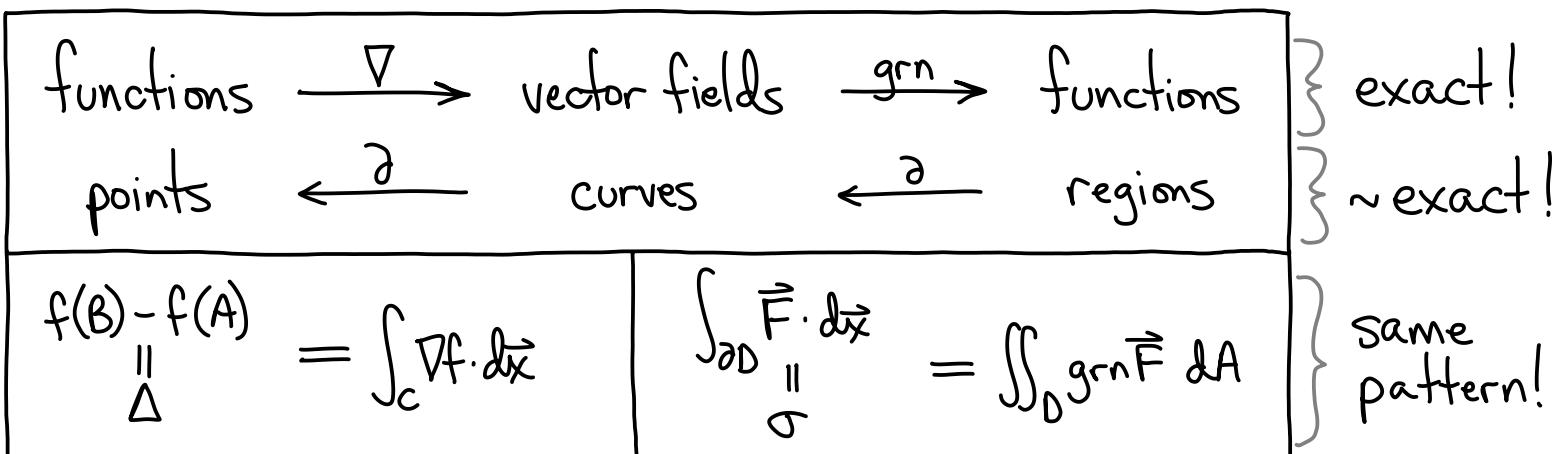
Ex: Is $\vec{F} = (-y, x)$ a gradient?

$$\text{grn } \vec{F} = \frac{\partial(x)}{\partial x} - \frac{\partial(-y)}{\partial y} = 2 \neq 0, \text{ so } \underline{\text{no}}.$$

(Alt: If it were, then all of these vectors would be pointing uphill!
Escher stairs!)



Strategic diagram for \mathbb{R}^2



- Organizes objects, relationships, properties
(gradient (conservative) = path independent = irrotational)
- Suggests things to try, what you need!

Ex: Considering $\int_C \vec{F} \cdot d\vec{x}$...

- ① Diagram asks if $\vec{F} = \nabla f$ — and suggests computing $\operatorname{grad} \vec{F}$ to decide.
- ② Diagram asks if $C = \partial D$ — and suggests looking at bdry points to decide.

We will soon see a similar diagram for \mathbb{R}^3 !

Finding antigradients

If $\vec{F} = \begin{pmatrix} P \\ Q \\ R \end{pmatrix}$ is $\nabla f = \begin{pmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \\ \frac{\partial f}{\partial z} \end{pmatrix}$, then

$$\frac{\partial f}{\partial x} = P$$

$$\frac{\partial f}{\partial y} = Q$$

$$\frac{\partial f}{\partial z} = R$$

$$f = \begin{cases} \int P dx + c_1(y, z) \\ \int Q dy + c_2(x, z) \\ \int R dz + c_3(x, y) \end{cases}$$

Need to find f that satisfies all 3 of these requirements!

Ex:) Find an antigradient for $\vec{F} = (2xy+z, x^2-z^2, x-2yz)$.
 (Note that $\nabla \times \vec{F} = \vec{0}$, so we expect such an f to exist.)

$$\int P dx = \int 2xy + z dx = x^2y + xz + C_1(y, z)$$

$$\int Q dy = \int x^2 - z^2 dy = x^2y - yz^2 + C_2(x, z)$$

$$\int R dz = \int x - 2yz dz = xz - yz^2 + C_3(x, y)$$

Is there an f equal to all of these? Yes!

$$f = x^2y + xz - yz^2$$

Ex:) Will the above method find an antigradient for $\vec{F} = (-y, x)$? (Note $\text{grn } \vec{F} \neq 0$, so we expect such an \vec{F} should not exist.)

$$\int P dx = \int (-y) dx = -xy + C_1(y)$$

$$\int Q dy = \int (x) dy = xy + C_2(x)$$

Is there an f equal to all of these? No!