EXAM 3

Math 107, 2010-2011 Spring, Clark Bray.

You have 50 minutes.

No notes, no books, no calculators.

YOU MUST SHOW ALL WORK AND EXPLAIN ALL REASONING TO RECEIVE CREDIT. CLARITY WILL BE CONSIDERED IN GRADING.

All answers must be simplified. All of the policies and guidelines on the class webpages are in effect on this exam.

	Good luck!	
Name	Solutions	
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	Total Score	(/100 points)

1. (20 pts) Find the matrix $A = [T]_{S}^{S}$, given the information below:

$$[T]_{\nu}^{\nu} = \begin{pmatrix} 3 & 1 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

$$\nu = \{\vec{v}_{1}, \vec{v}_{2}, \vec{v}_{3}\}, \quad [\vec{v}_{1}]_{S} = \begin{bmatrix} 1 \\ 4 \\ -2 \end{bmatrix} \quad [\vec{v}_{2}]_{S} = \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} \quad [\vec{v}_{3}]_{S} = \begin{bmatrix} 2 \\ 5 \\ -2 \end{bmatrix}$$

$$\begin{pmatrix} -9 & 8 & 11 \\ -2 & 2 & 3 \\ 8 & -7 & -10 \end{pmatrix} \begin{pmatrix} 1 & 3 & 2 \\ 4 & 2 & 5 \\ -2 & 1 & -2 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 3 & 2 \\ 4 & 2 & 5 \\ -2 & 1 & -2 \end{pmatrix} \begin{pmatrix} 3 & 1 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} 1 & 3 & 2 \\ 4 & 2 & 5 \\ -2 & 1 & 2 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 3 & 2 \\ 4 & 2 & 5 \\ -2 & 1 & 2 \end{pmatrix} \begin{pmatrix} 3 & 1 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 2 \end{pmatrix} \begin{pmatrix} 1 & 3 & 2 \\ 4 & 2 & 5 \\ -2 & 1 & 2 \end{pmatrix}$$

$$= \begin{pmatrix} 3 & (0 & 4) \\ 12 & (0 & (0) \\ -6 & 1 & -4 \end{pmatrix} \begin{pmatrix} -9 & 8 & 11 \\ -2 & 2 & 3 \\ 8 & -7 & -10 \end{pmatrix}$$

$$= \begin{pmatrix} -15 & 16 & 23 \\ -48 & 46 & 62 \\ 20 & -18 & -23 \end{pmatrix}$$

2. (30 pts) Find a Jordan basis and the Jordan canonical form for the matrix

$$\int_{0}^{7} \int_{0}^{6} \frac{1}{3} \int_{0}^{7} \int_{0}^{6} \frac{1}{3} \int_{0}^{7} \int_{0}^{6} \int_{0}^{7} \int_{0}^{7$$

(extra space if needed)

$$M \tilde{J}_2 = \tilde{J}_1$$

$$\begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & -1/3 \\ 0 & 0 & 0 \end{pmatrix} \overrightarrow{J}_{2} = \begin{pmatrix} -1 & -1 & 1 \\ y_{2} & y_{3} & 0 \\ 4 & 3 & -5 \end{pmatrix} \begin{pmatrix} 3 \\ 1 \\ 3 \end{pmatrix} = \begin{pmatrix} -1 \\ 4/3 \\ 0 \end{pmatrix}$$

Choosing
$$z=0$$
, we get $V_2=\begin{pmatrix} -1\\4/3\\0 \end{pmatrix}$

To find V3, we solve

$$M\vec{V}_3 = \vec{V}_2$$

Choosing
$$z=0$$
, we get $\sqrt{3}=\begin{pmatrix} -1/3\\ 1/4\\ 0 \end{pmatrix}$

So
$$\left\{ \begin{pmatrix} 3\\1\\3 \end{pmatrix}, \begin{pmatrix} -1\\4/3\\0 \end{pmatrix}, \begin{pmatrix} -1/3\\1/9\\0 \end{pmatrix} \right\}$$
 is a Jordan basis.

3. (10 pts) Show by direct calculation that the Hermitian transpose, defined by $A^* = \bar{A}^T$, satisfies the following equation.

$$\langle A\vec{v}, \vec{w} \rangle_H = \langle \vec{v}, A^*\vec{w} \rangle_H$$

$$\langle Av, v \rangle_{A} = \langle Av, v \rangle_{A}$$

$$= \langle v \rangle_{A} \langle v \rangle_{A}$$

4. (20 pts) Find a fundamental set of solutions to the system of differential equations described by $\vec{y}' = A\vec{y}$, where

$$A = \begin{pmatrix} 4 & 1 & -3 \\ 43 & -7 & 191 \\ 3 & -1 & 18 \end{pmatrix}$$

Here is some arithmetic that you might find useful:

is some arithmetic that you might find useful:
$$\begin{pmatrix}
4 & 1 & -3 \\
43 & -7 & 191 \\
3 & -1 & 18
\end{pmatrix} = \begin{pmatrix}
5 & 2 & 1 \\
2 & 7 & 3 \\
-1 & 0 & 0
\end{pmatrix} \begin{pmatrix}
5 & 1 & 0 \\
0 & 5 & 1 \\
0 & 0 & 5
\end{pmatrix} \begin{pmatrix}
0 & 0 & -1 \\
-3 & 1 & -13 \\
7 & -2 & 31
\end{pmatrix}$$

$$\begin{pmatrix}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{pmatrix} = \begin{pmatrix}
5 & 2 & 1 \\
2 & 7 & 3 \\
-1 & 0 & 0
\end{pmatrix} \begin{pmatrix}
0 & 0 & -1 \\
-3 & 1 & -13 \\
7 & -2 & 31
\end{pmatrix}$$

The above tells us that

So J is the Jordan canonical form for A, and the

$$\overrightarrow{V}_{1} = \begin{pmatrix} 5 \\ 2 \\ -1 \end{pmatrix} \qquad \overrightarrow{V}_{2} = \begin{pmatrix} 2 \\ 7 \\ 0 \end{pmatrix} \qquad \overrightarrow{V}_{3} = \begin{pmatrix} 1 \\ 3 \\ 0 \end{pmatrix}$$

form a Jordan basis

So a fundamental set of solutions is {exAt, exAt, exAt, exAt}

$$6 \times 1 = 6 \times 1 = 6 \times \left(\frac{-1}{2}\right)$$

$$e^{A} \vec{J}_{z} = e^{S \times (\vec{J}_{z} + \times \vec{J}_{i})} = e^{S \times (\frac{z + S \times}{7 + 2 \times})}$$

$$e^{\lambda} \vec{J}_{z} = e^{S \times \left(\vec{J}_{z} + \times \vec{J}_{1}\right)} = e^{S \times \left(\frac{2 + S \times}{7 + 2 \times}\right)}$$

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5. (20 pts) Find a particular solution to the system of differential equations $\vec{y}' = A\vec{y} + \vec{g}$, with

$$A = \begin{pmatrix} -5 & -3 \\ 2 & 0 \end{pmatrix} \quad \text{and} \quad \vec{g}(x) = \begin{bmatrix} 0 \\ x \end{bmatrix}$$

(In case it might be useful, note that the vectors (3,-2) and (-1,1) are eigenvectors.)

We gress
$$\vec{y} = \vec{a} + \vec{b} \times .$$
 The equation becomes $(\vec{a} + \vec{b} \times)' = A(\vec{a} + \vec{b} \times) + \times (i)$
 $\vec{b} = A\vec{a} + (A\vec{b} + (i)) \times$

So we must have

$$Ab = \begin{pmatrix} 0 \\ -1 \end{pmatrix} \qquad \text{and} \qquad Aa = b$$

$$b = A^{-1} \begin{pmatrix} 0 \\ -1 \end{pmatrix} \qquad a = A^{-1} \begin{pmatrix} -1/2 \\ 5/6 \end{pmatrix}$$

$$b = \begin{pmatrix} 0 & 3 \\ -2 & -5 \end{pmatrix} \begin{pmatrix} 0 \\ -1 \end{pmatrix} \qquad a = \begin{pmatrix} 0 & 3 \\ -2 & -5 \end{pmatrix} \begin{pmatrix} -1/2 \\ 5/6 \end{pmatrix}$$

$$b = \begin{pmatrix} -1/2 \\ 5/6 \end{pmatrix} \qquad a = \begin{pmatrix} 5/12 \\ -19/36 \end{pmatrix}$$

So our particular solution is

$$\overrightarrow{J_p} = \overrightarrow{a} + \overrightarrow{b} \times = \begin{pmatrix} 5/12 & -\frac{1}{2} \times \\ -19/36 & +\frac{5}{6} \times \end{pmatrix}$$